

Semantic Theory

Lecture 14: Dynamic Predicate Logic

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Contributions of DRT

- (1) *A student works. She is successful.*
- (2) *If a student works, she is successful.*

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Sentence Meaning (Recap)

- **Truth-conditional interpretation:** The meaning of a declarative sentence is given by its truth conditions
- **Compositionality:** The meaning of a complex expression is a function of the meanings of its parts and of the syntactic rules by which they are combined

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Accessibility & Truth-conditions

- (1) *There is a book that John doesn't own.
He wants to buy it.*
- (2) *John does not own every book.
* He wants to buy it.*
- (3) *One of the ten balls is not in the bag.
It must be under the sofa.*
- (4) *Nine of the ten balls are in the bag.
* It must be under the sofa.*

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DRT & Compositionality

- **DRT is non-compositional** on truth conditions: The different discourse-semantic status of the text pairs is not predictable through the (identical) truth conditions of its component sentences.
- Since structural information which cannot be reduced to truth conditions is required to compute the semantic value of texts, DRT is called **a representational theory of meaning**.

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Dynamic Predicate Logic (DPL)

- **Dynamic Predicate Logic** is a dynamic theory of meaning (just like DRT) but admits (in contrast to DRT) a compositional interpretation
- **The DRT approach:**
 - alternative representations ("boxes")
 - interpretation not fully compositional
- **The DPL approach:**
 - conventional representations (predicate logic)
 - compositional (but more complex) interpretation

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Dynamic Predicate Logic (DPL)

- The DPL approach is closely related to the denotational approach to the semantics of programming languages.
- A program p denotes a set of pairs of start and end configurations:
 - $\langle f, g \rangle \in \llbracket p \rrbracket^M$ iff g is an end configuration that can be reached from the start configuration f by running p .
- Semantics of complex programs can be determined compositionally. For instance:
 - $\langle f, g \rangle \in \llbracket p_1; p_2 \rrbracket^M$ iff there is an intermediate configuration h that can be reached from f by running p_1 ($\langle f, h \rangle \in \llbracket p_1 \rrbracket^M$) and from which g can be reached by running p_2 ($\langle h, g \rangle \in \llbracket p_2 \rrbracket^M$)

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Dynamic Predicate Logic (DPL)

- Logical formulas are programs. Configurations are variable assignments.
- A formula denotes a set of pairs of start and end configurations (input and output assignments).
 - $\llbracket \varphi \rrbracket^M = \{ \langle g, h \rangle \mid \dots \}$
- Certain formulas and connectives are instructions for changing the assignments.
 - for instance: “ $\exists x$ ” modifies the value of x by overwriting it with an arbitrary individual from the universe.
- Other formulas are tests: “ $F(x)$ ” checks whether the value of x in the current assignment has the property F .

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Syntax of DPL

- The syntax of dynamic predicate logic (DPL) is the syntax of first-order predicate logic.
- Translation of natural languages expressions into DPL:
 - “ a ” and “every” into the respective quantifier
 - pronouns into (possibly free) variables.
- Example:
 - Somebody works. She is successful.
 - $\exists x \text{ work}(x) \wedge \text{successful}(x)$
 - **Note:** “ x ” in the right conjunct not in the scope of “ $\exists x$ ”

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Semantics of DPL

- Ordinary first order model structures
 - Universe + interpretation function
- **Interpretation of terms** as in predicate logic
 - $\llbracket c \rrbracket^{M,g} = V_M(c)$ (constants)
 - $\llbracket x \rrbracket^{M,g} = g(x)$ (variables)
- **Interpretation of formulae:** The semantic value $\llbracket \varphi \rrbracket$ of a formula φ is a binary relation between variable assignments:
 - $\llbracket \varphi \rrbracket^M = \{ \langle g, h \rangle \mid \dots \}$

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Semantics of DPL

- **Atomic Formulae:**
 - $\llbracket R(t_1, \dots, t_n) \rrbracket^M = \{ \langle g, h \rangle \mid g=h \wedge \langle \llbracket t_1 \rrbracket^{M,g}, \dots, \llbracket t_n \rrbracket^{M,g} \rangle \in V_M(R) \}$
- **Existential quantification:**
 - $\llbracket \exists x \varphi \rrbracket^M = \{ \langle g, h \rangle \mid \exists k: k[x]g \wedge \langle k, h \rangle \in \llbracket \varphi \rrbracket^M \}$
- Read “**h[x]g**” as “assignments h and g differ at most in the value for x”

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Example (\exists)

- *Somebody works.*
 - $\exists x \text{work}(x)$
- **Interpretation:**
 - $\langle g, h \rangle \in \llbracket \exists x \text{work}(x) \rrbracket^M$
 - iff there is a k such that $k[x]g$ and $\langle k, h \rangle \in \llbracket \text{work}(x) \rrbracket^M$
 - iff there is a k such that $k[x]g$ and $\langle k, h \rangle \in \{ \langle k', h' \rangle \mid k' = h' \text{ and } \llbracket x \rrbracket^{M,h'} \in V_M(\text{work}) \}$
 - iff there is a k such that $k[x]g$ and $k = h$ and $\llbracket x \rrbracket^{M,h} \in V_M(\text{work})$
 - iff $h[x]g$ and $\llbracket x \rrbracket^{M,h} \in V_M(\text{work})$

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Example (\exists)

- *Somebody works.*
 - $\exists x \text{ work}(x)$
- **Interpretation:**
 - $\langle g, h \rangle \in \llbracket \exists x \text{ work}(x) \rrbracket^M$ iff $h[x]g$ and $\llbracket x \rrbracket^{M,h} \in V_M(\text{work})$
- Alternative notation:
 - $\llbracket \exists x \text{ work}(x) \rrbracket^M = \{ \langle g, h \rangle \mid h[x]g \text{ and } \llbracket x \rrbracket^{M,h} \in V_M(\text{work}) \}$

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Conjunctions

- *Somebody works. She is successful*
 - $\exists x \text{ work}(x) \wedge \text{successful}(x)$

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Conjunctions

- Atomic Formulae:
 - $\llbracket R(t_1, \dots, t_n) \rrbracket^M = \{ \langle g, h \rangle \mid g=h \wedge \langle \llbracket t_1 \rrbracket^{M,g}, \dots, \llbracket t_n \rrbracket^{M,g} \rangle \in V_M(R) \}$
- Existential quantification:
 - $\llbracket \exists x \varphi \rrbracket^M = \{ \langle g, h \rangle \mid \exists k: k[x]g \wedge \langle k, h \rangle \in \llbracket \varphi \rrbracket^M \}$
- **Conjunctions:**
 - $\llbracket \varphi \wedge \psi \rrbracket^M = \{ \langle g, h \rangle \mid \exists k: \langle g, k \rangle \in \llbracket \varphi \rrbracket^M \wedge \langle k, h \rangle \in \llbracket \psi \rrbracket^M \}$

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Conjunctions

- *Somebody works. She is successful*
 - $\exists x \text{work}(x) \wedge \text{successful}(x)$
- **Interpretation:**
 - $\langle g, h \rangle \in \llbracket \exists x \text{work}(x) \wedge \text{successful}(x) \rrbracket^M$
 - iff there is a k such that
 - $\langle g, k \rangle \in \llbracket \exists x \text{work}(x) \rrbracket^M$ and $\langle k, h \rangle \in \llbracket \text{successful}(x) \rrbracket^M$
 - iff there is a k such that
 - $k[x]g$ and $k(x) \in V_M(\text{work})$ and $k = h$ and $k(x) \in V_M(\text{successful})$

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Static & dynamic operators

- Existential quantifiers are dynamic operators:
 - the output assignment of a formula $\exists x\psi$ can be different than the input assignment
- Conjunctions are also interpreted dynamically
 - the left-hand subformula can change the input assignment for the right-hand subformula
- Atomic formulae are interpreted statically:
 - input and output assignment must be identical

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Conditionals

- *If somebody works, she is successful*
 - $\exists x \text{work}(x) \rightarrow \text{successful}(x)$

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Conditionals

- Atomic Formulae:
 - $\llbracket R(t_1, \dots, t_n) \rrbracket^M = \{ \langle g, h \rangle \mid g = h \wedge \langle \llbracket t_1 \rrbracket^{M,g}, \dots, \llbracket t_n \rrbracket^{M,g} \rangle \in V_M(R) \}$
- Conjunctions
 - $\llbracket \varphi \wedge \psi \rrbracket^M = \{ \langle g, h \rangle \mid \exists k: \langle g, k \rangle \in \llbracket \varphi \rrbracket^M \wedge \langle k, h \rangle \in \llbracket \psi \rrbracket^M \}$
- Existential quantification:
 - $\llbracket \exists x \varphi \rrbracket^M = \{ \langle g, h \rangle \mid \exists k: k[x]g \wedge \langle k, h \rangle \in \llbracket \varphi \rrbracket^M \}$
- **Conditionals:**
 - $\llbracket \varphi \rightarrow \psi \rrbracket^M = \{ \langle g, h \rangle \mid g = h \wedge \forall k: \langle g, k \rangle \in \llbracket \varphi \rrbracket^M \Rightarrow \exists j: \langle k, j \rangle \in \llbracket \psi \rrbracket^M \}$

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Conditionals

- *If somebody works, she is successful*
 - $\exists x \text{work}(x) \rightarrow \text{successful}(x)$
- **Interpretation:**
 - $\langle g, h \rangle \in \llbracket \exists x \text{work}(x) \rightarrow \text{successful}(x) \rrbracket^M$
 - iff $g = h$ and for all k :
 - if $\langle h, k \rangle \in \llbracket \exists x \text{work}(x) \rrbracket^M$,
 - then there is a j such that $\langle k, j \rangle \in \llbracket \text{successful}(x) \rrbracket^M$
 - iff $g = h$ and for all k :
 - if $k[x]h$ and $k(x) \in V_M(\text{work})$,
 - then there is a j such that $k = j$ and $j(x) \in V_M(\text{successful})$

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Conditionals

- *If somebody works, she is successful*
 - $\exists x \text{work}(x) \rightarrow \text{successful}(x)$
- **Interpretation:**
 - $\langle g, h \rangle \in \llbracket \exists x \text{work}(x) \rightarrow \text{successful}(x) \rrbracket^M$
 - iff $g = h$ and for all k :
 - if $k[x]h$ and $k(x) \in V_M(\text{work})$, then $k(x) \in V_M(\text{successful})$

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Universals, Disjunction, Negation

- **Negation**

- $\llbracket \neg\phi \rrbracket^M = \{ \langle g, h \rangle \mid g = h \wedge \neg \exists k: \langle g, k \rangle \in \llbracket \phi \rrbracket^M \}$

- **Disjunction**

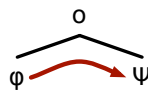
- $\llbracket \phi \vee \psi \rrbracket^M = \{ \langle g, h \rangle \mid g=h \wedge \exists k: \langle g, k \rangle \in \llbracket \phi \rrbracket^M \vee \langle g, k \rangle \in \llbracket \psi \rrbracket^M \}$

- **Universal quantification**

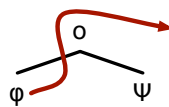
- $\llbracket \forall x\phi \rrbracket^M = \{ \langle g, h \rangle \mid g = h \wedge \forall k: k[x]g \Rightarrow \exists m: \langle k, m \rangle \in \llbracket \phi \rrbracket^M \}$

Static & dynamic operators

- A connective o is **internally dynamic** iff the left-hand subformula can change the input assignment for the right-hand subformula



- A connective o is **externally dynamic** iff the output assignment of a formula with main connective o can be different than the input assignment



- Formulas whose main connective is externally static are called **tests**: From $\langle g, h \rangle \in \llbracket \phi \rrbracket^M$ follows that $g = h$

Connectives: Overview

Connective	externally	internally
\neg	static	-
\wedge	dynamic	dynamic
\vee	static	static
\rightarrow	static	dynamic
\exists	dynamic	dynamic
\forall	static	dynamic

Semantics of DPL

- **Interpretation of formulas** with respect to a model structure M and variable assignment g .

$$\llbracket R(t_1, \dots, t_n) \rrbracket^M = \{ \langle g, h \rangle \mid g = h \wedge \langle \llbracket t_1 \rrbracket^{M,g}, \dots, \llbracket t_n \rrbracket^{M,g} \rangle \in V_M(R) \}$$

$$\llbracket t_1 = t_2 \rrbracket^M = \{ \langle g, h \rangle \mid g = h \wedge \llbracket t_1 \rrbracket^{M,g} = \llbracket t_2 \rrbracket^{M,g} \}$$

$$\llbracket \neg \varphi \rrbracket^M = \{ \langle g, h \rangle \mid g = h \wedge \neg \exists k: \langle g, k \rangle \in \llbracket \varphi \rrbracket^M \}$$

$$\llbracket \varphi \wedge \psi \rrbracket^M = \{ \langle g, h \rangle \mid \exists k: \langle g, k \rangle \in \llbracket \varphi \rrbracket^M \wedge \langle k, h \rangle \in \llbracket \psi \rrbracket^M \}$$

$$\llbracket \varphi \vee \psi \rrbracket^M = \{ \langle g, h \rangle \mid g = h \wedge \exists k: \langle g, k \rangle \in \llbracket \varphi \rrbracket^M \vee \langle g, k \rangle \in \llbracket \psi \rrbracket^M \}$$

$$\llbracket \varphi \rightarrow \psi \rrbracket^M = \{ \langle g, h \rangle \mid g = h \wedge \forall k: \langle g, k \rangle \in \llbracket \varphi \rrbracket^M \Rightarrow \exists j: \langle k, j \rangle \in \llbracket \psi \rrbracket^M \}$$

$$\llbracket \exists x \varphi \rrbracket^M = \{ \langle g, h \rangle \mid \exists k: k[x]g \wedge \langle k, h \rangle \in \llbracket \varphi \rrbracket^M \}$$

$$\llbracket \forall x \varphi \rrbracket^M = \{ \langle g, h \rangle \mid g = h \wedge \forall k: k[x]g \Rightarrow \exists m: \langle k, m \rangle \in \llbracket \varphi \rrbracket^M \}$$

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Truth & Validity

- A formula φ is **true in M with respect to** an input assignment g iff there is a h such that $\langle g, h \rangle \in \llbracket \varphi \rrbracket^M$
- A formula φ is **true in M** iff φ is true in M wrt. every input assignment g .
- A formula φ is **valid** iff φ is true in every model structure M .

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Equivalence

- **Satisfaction set** of a formula φ in M :
 $\backslash \varphi \backslash_M = \{ g \mid \text{there is a } h \text{ such that } \langle g, h \rangle \in \llbracket \varphi \rrbracket^M \}$
- **Static equivalence** (s-equivalence)
 $\varphi \Leftrightarrow_s \psi$ iff for all model structures M : $\backslash \varphi \backslash_M = \backslash \psi \backslash_M$
- **Equivalence** (dynamic / full equivalence):
 $\varphi \Leftrightarrow \psi$ iff for all model structures M : $\llbracket \varphi \rrbracket^M = \llbracket \psi \rrbracket^M$

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Entailment

- **Static entailment:** $\varphi \models_s \psi$
iff for all model structures M and assignments g: if φ is true in M for g, then ψ is true in M for g
- **Meaning Inclusion:** $\varphi \leq \psi$
iff for all model structures M, $\llbracket \varphi \rrbracket^M \subseteq \llbracket \psi \rrbracket^M$
- **Dynamic entailment:** $\varphi \models \psi$
iff for all model structures M and assignments g and h: if $\langle g, h \rangle \in \llbracket \varphi \rrbracket$, then there is an assignment k such that $\langle h, k \rangle \in \llbracket \psi \rrbracket$

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Logical Properties

- **The following equivalences hold:**
 - $\exists x A \wedge B \Leftrightarrow \exists x (A \wedge B)$
 - $\exists x A \rightarrow B \Leftrightarrow \forall x (A \rightarrow B)$
 - $(A \wedge B) \wedge C \Leftrightarrow A \wedge (B \wedge C)$
 - $A \rightarrow (B \rightarrow C) \Leftrightarrow (A \wedge B) \rightarrow C$
 - $A \vee B \Leftrightarrow B \vee A$
- **The following equivalences do not hold:**
 - $A \wedge B \Leftrightarrow B \wedge A$
 - $A \Leftrightarrow A \wedge A$
 - $\neg \forall x A \Leftrightarrow \exists x \neg A$

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Definability of Connectives

- \vee , \rightarrow and \forall can be defined from \neg , \wedge und \exists
- But not vice versa!
- **Equivalences**
 - $A \rightarrow B \Leftrightarrow \neg(A \wedge \neg B)$
 - $A \vee B \Leftrightarrow \neg(\neg A \wedge \neg B)$
 - $A \vee B \Leftrightarrow \neg A \rightarrow B$
 - $\forall x A \Leftrightarrow \neg \exists x \neg A$
- **Non-equivalences**
 - $A \wedge B \Leftrightarrow \neg(A \rightarrow \neg B)$
 - $A \wedge B \not\equiv_s \neg(\neg A \vee \neg B)$
 - $A \rightarrow B \not\equiv_s \neg A \vee B$
 - $\exists x A \Leftrightarrow \neg \forall x \neg A$

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Summary

- We can give a compositional interpretation to a theory of dynamic semantics:
 - relation between variable assignments.
- DPL uses standard syntax of predicate logic, but the different interpretation makes for interesting logical properties
 - for instance, some equivalences break
- We can translate DRSs into DPL formulas and further into (static) predicate logic formulas (see exercise).
- DRT can be equipped directly with a DPL-style interpretation.

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Literature

- Jeroen Groenendijk, Martin Stokhof. *Dynamic Predicate Logic*. *Linguistics and Philosophy*, Vol. 14(1), 1991.
- L.T.F. Gamut (1991): *Logic, Language and Meaning, Vol II*, University of Chicago Press. Chapter 7.4.5

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