

VISUAL ATTENTION  
IN SPOKEN  
HUMAN-ROBOT INTERACTION  
(HRI)

**Maria Staudte & Matthew Crocker**

# HUMANS...

- In Language Production
  - Referential gaze about 1 s before speech onset
- In Language Comprehension
  - Listeners gaze at referent approx. 200-500 ms after offset
- Alignment, Joint attention
  - 2 sec span between speaker's and listener's gaze
  - Joint attention speeds this up

# RESEARCH QUESTIONS

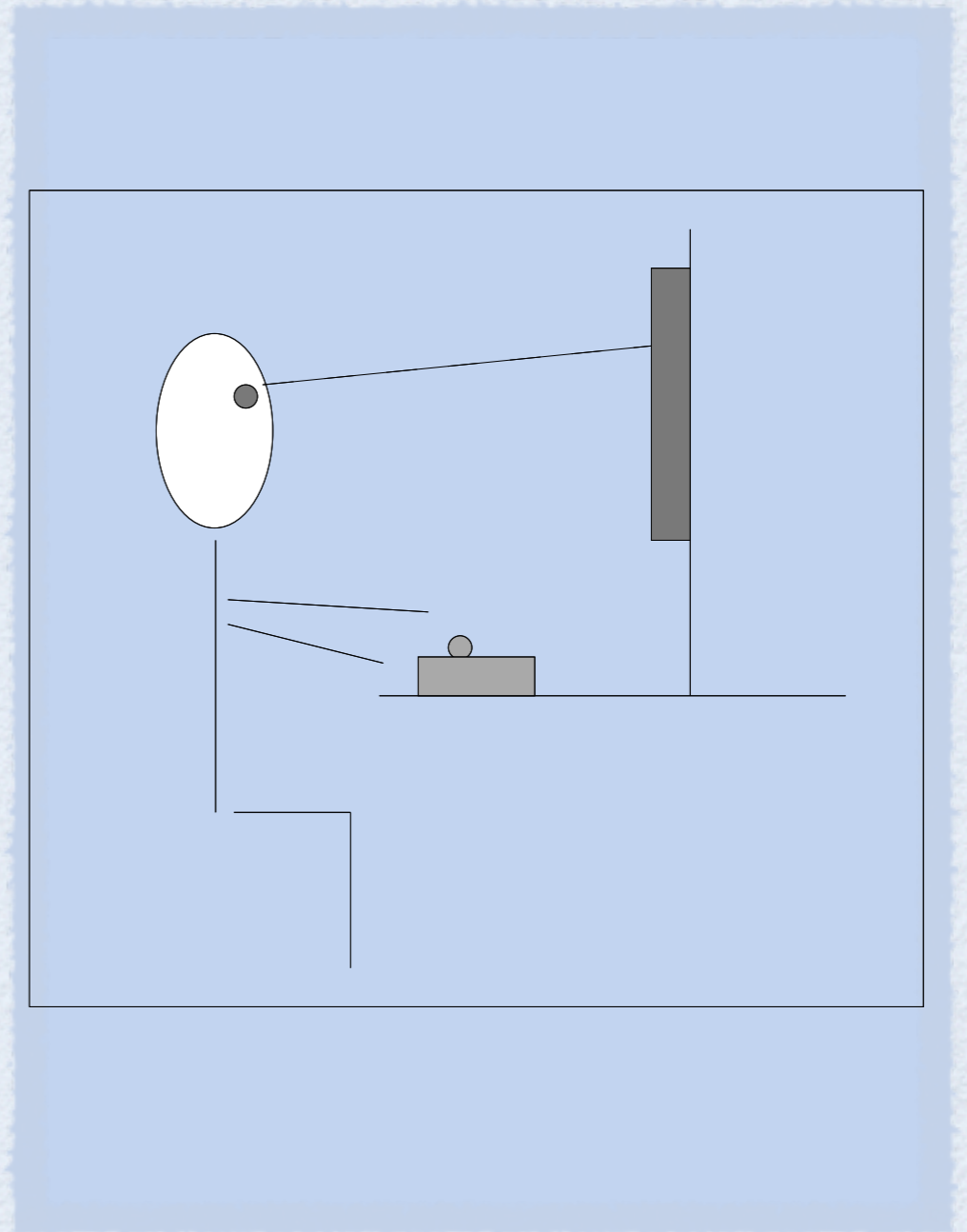
- Is robot gaze that reflects this pattern beneficial for human interaction partners?
- If so, what happens if this behaviour is inconsistent?

# METHODOLOGY

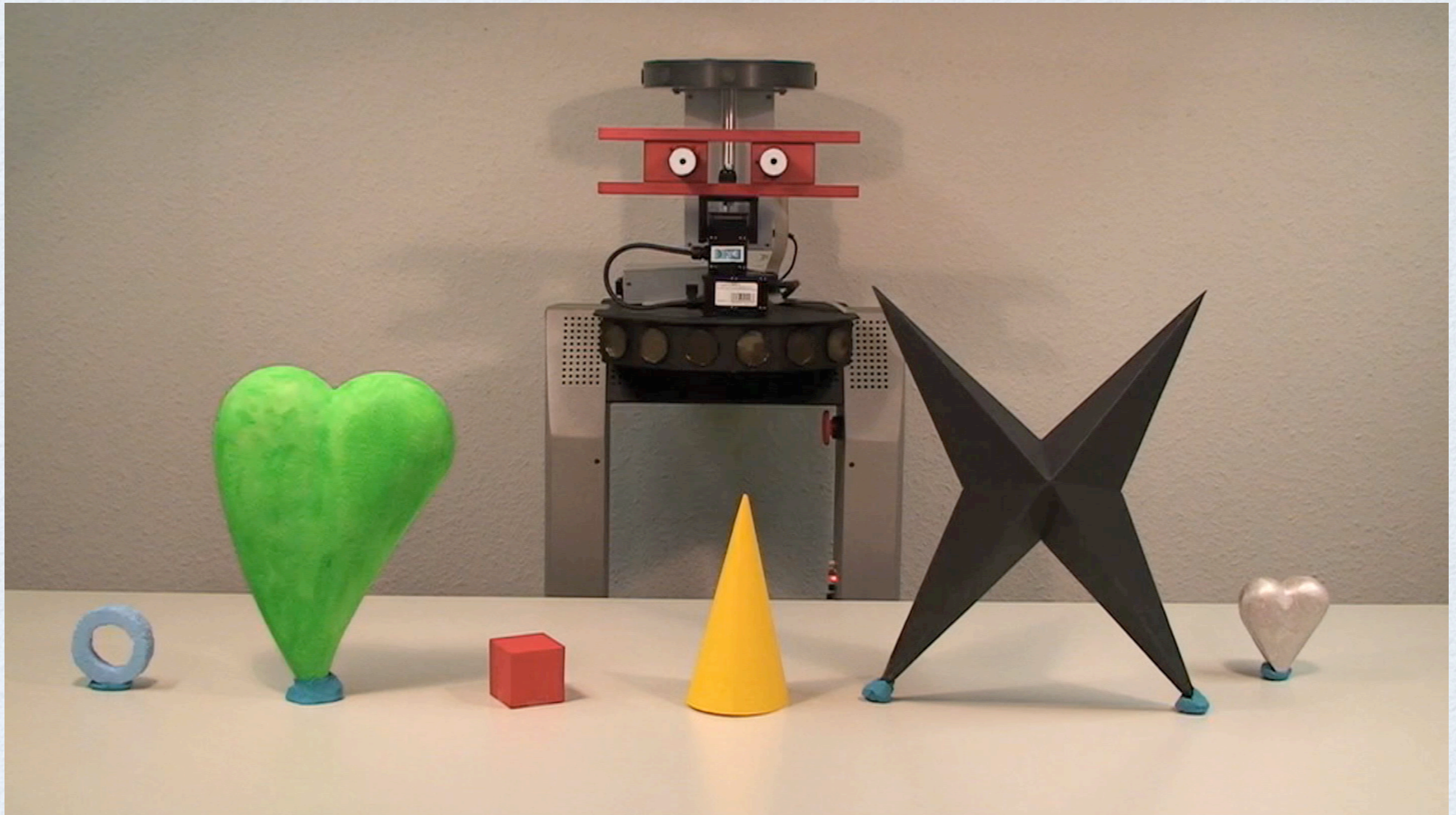
- Paradigm for measuring contribution of cognitively motivated robot gaze to HRI
  - Simulate *production* patterns from HHI
  - Apply to HRI
  - Monitor and evaluate participants' behaviour using precise methods from HHI

# DESIGN

- Record video clip of robot producing utterances and gaze about scene
- Video is played back to participants
- Participants are being eye-tracked while observing robot
- Task: after each clip participant determines truth of the robot's statement and presses a button



“The cone is taller than the heart that is silver.”

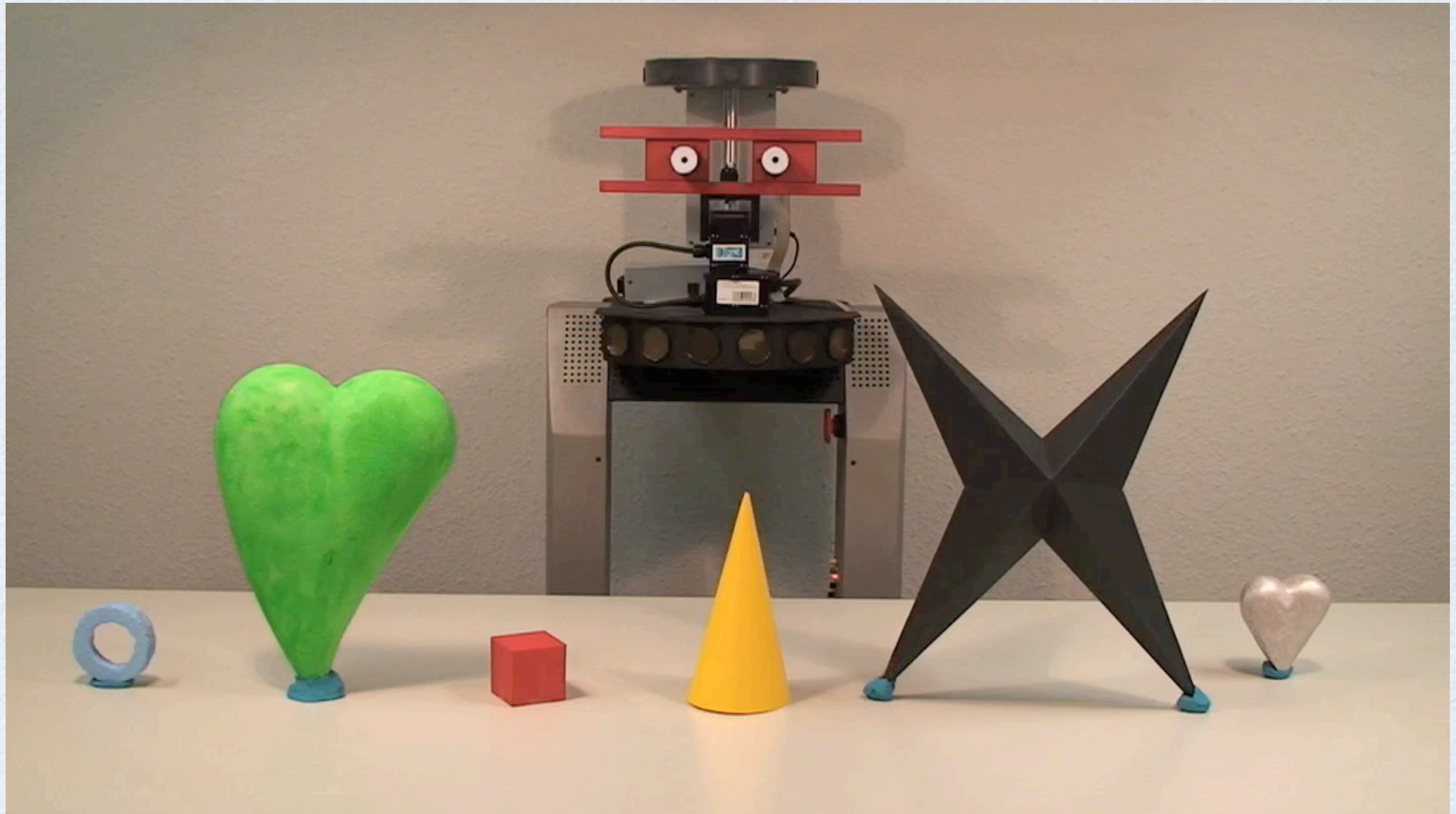


“The cone is taller than the heart that is silver.”

# DESIGN

- 2 Factors:
  - statement truth (true, false)
  - gaze congruency (congruent, incongruent, no gaze)
  - = 6 conditions
- 24 items, 48 fillers
- 48 participants

“The cone is taller than the heart that is silver.”



“The cone is taller than the heart that is silver.”

# ANALYSIS

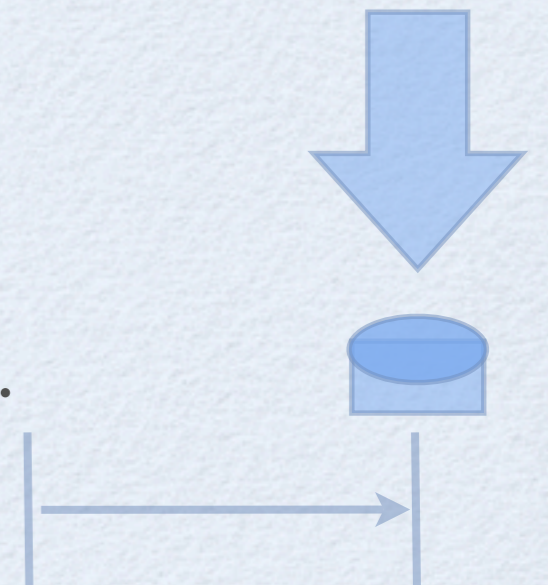
# ANALYSIS

- Recording response times

# ANALYSIS

- Recording response times

The cone is taller than the heart that is silver.



# ANALYSIS

- Recording response times

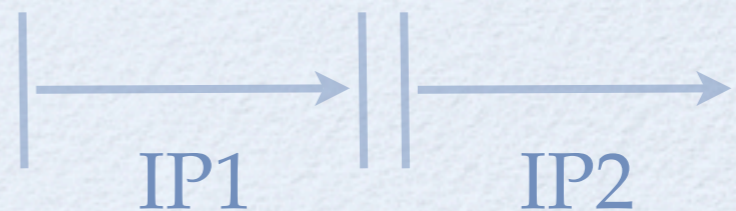
# ANALYSIS

- Recording response times
- Segmentation into interest areas (IAs) and interest periods (IPs)

# ANALYSIS

- Recording response times
- Segmentation into interest areas (IAs) and interest periods (IPs)

The cone is taller than the heart that is silver.



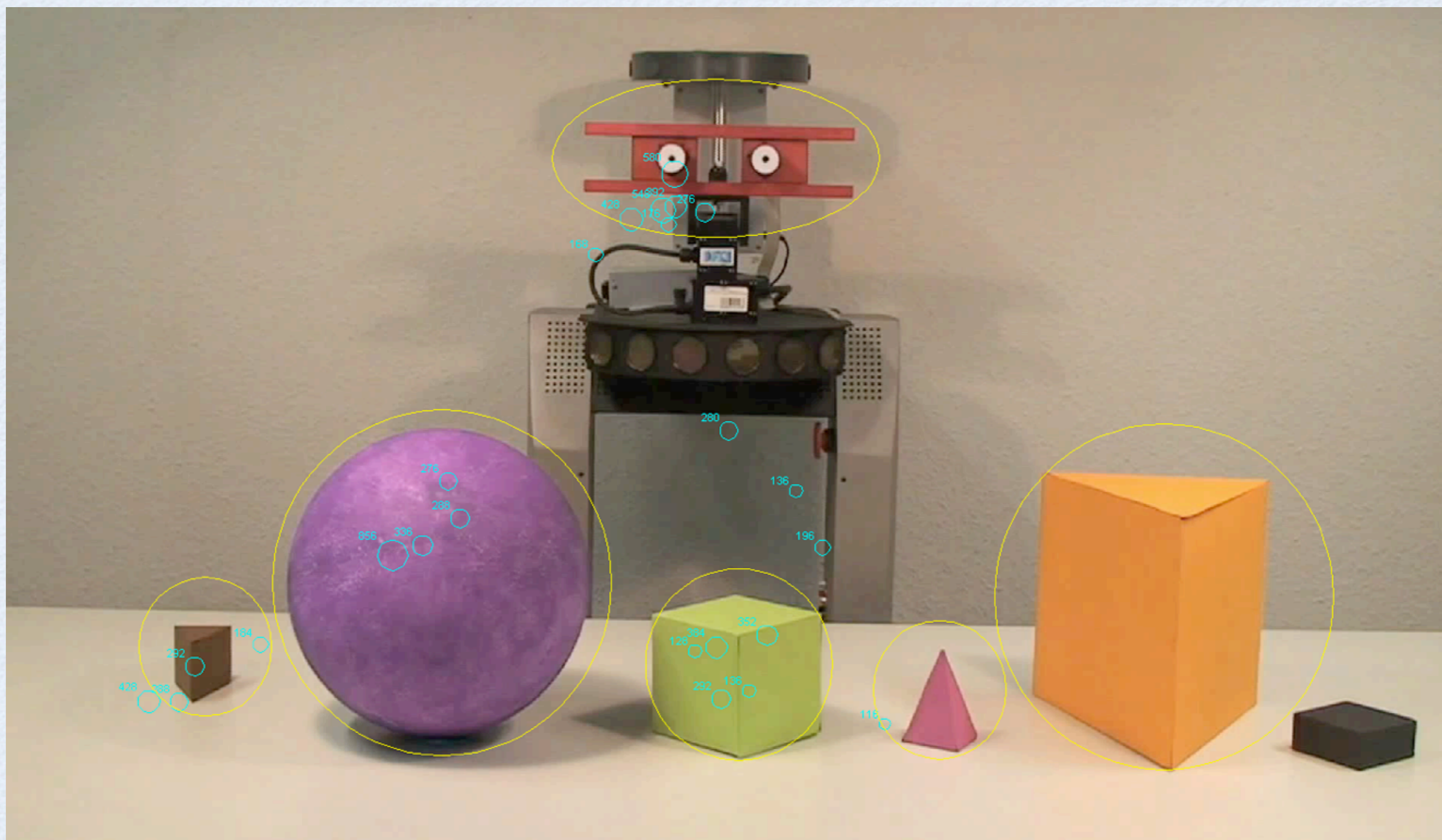
# ANALYSIS

- Recording response times
- Segmentation into interest areas (IAs) and interest periods (IPs)

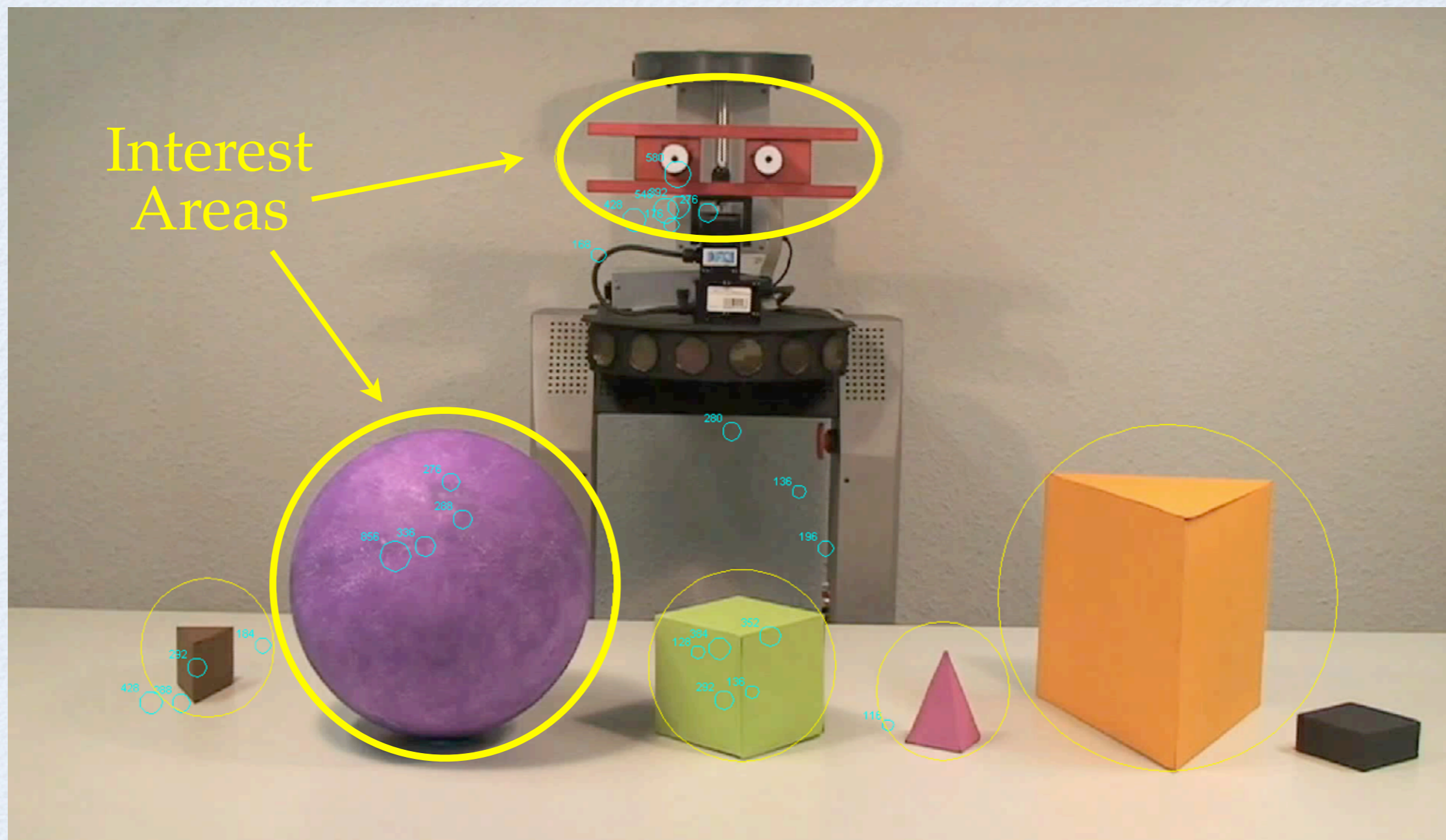
# ANALYSIS

- Recording response times
- Segmentation into interest areas (IAs) and interest periods (IPs)
- Fixations per IA & IP

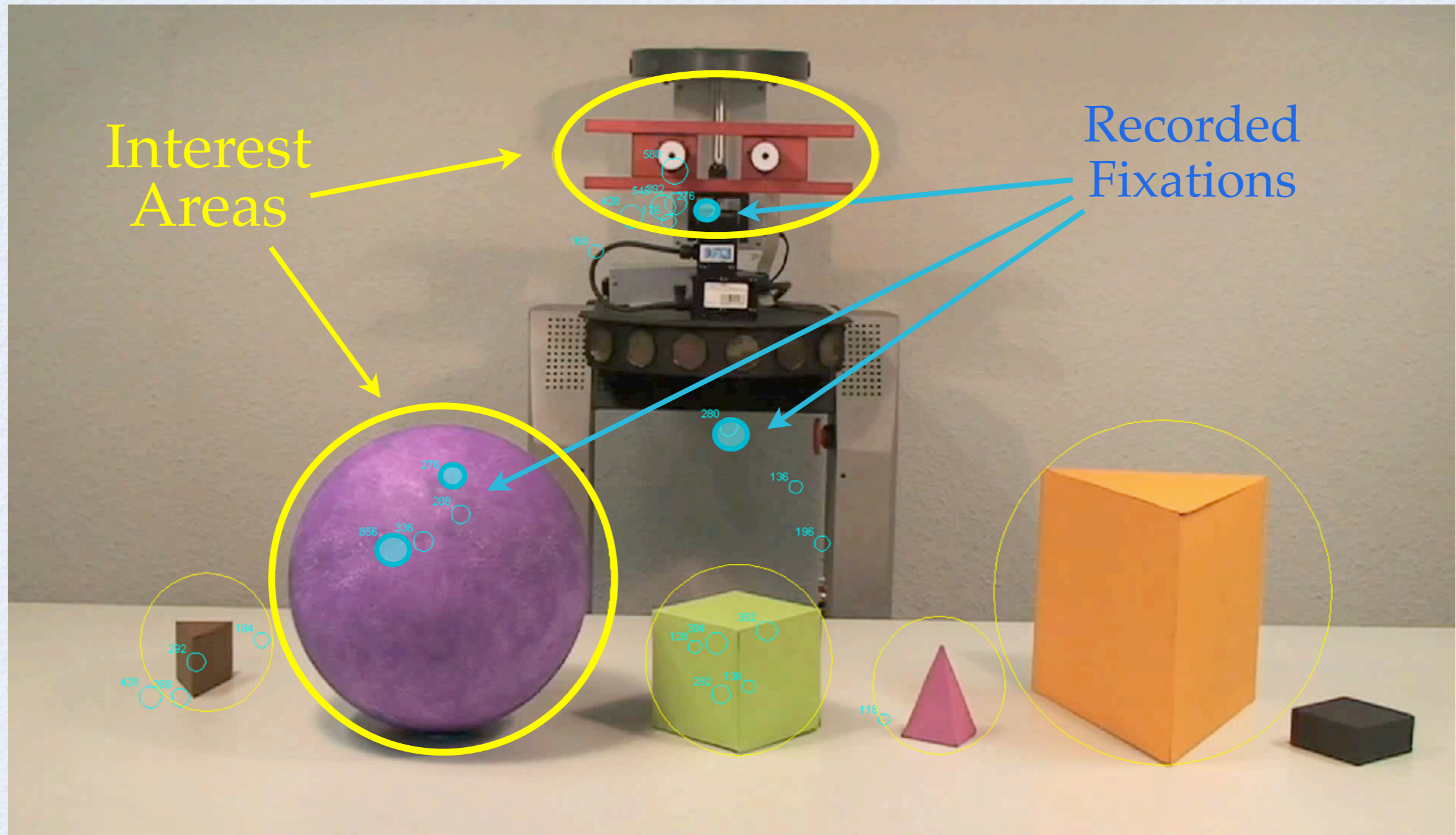
# IA, IP & FIXATIONS



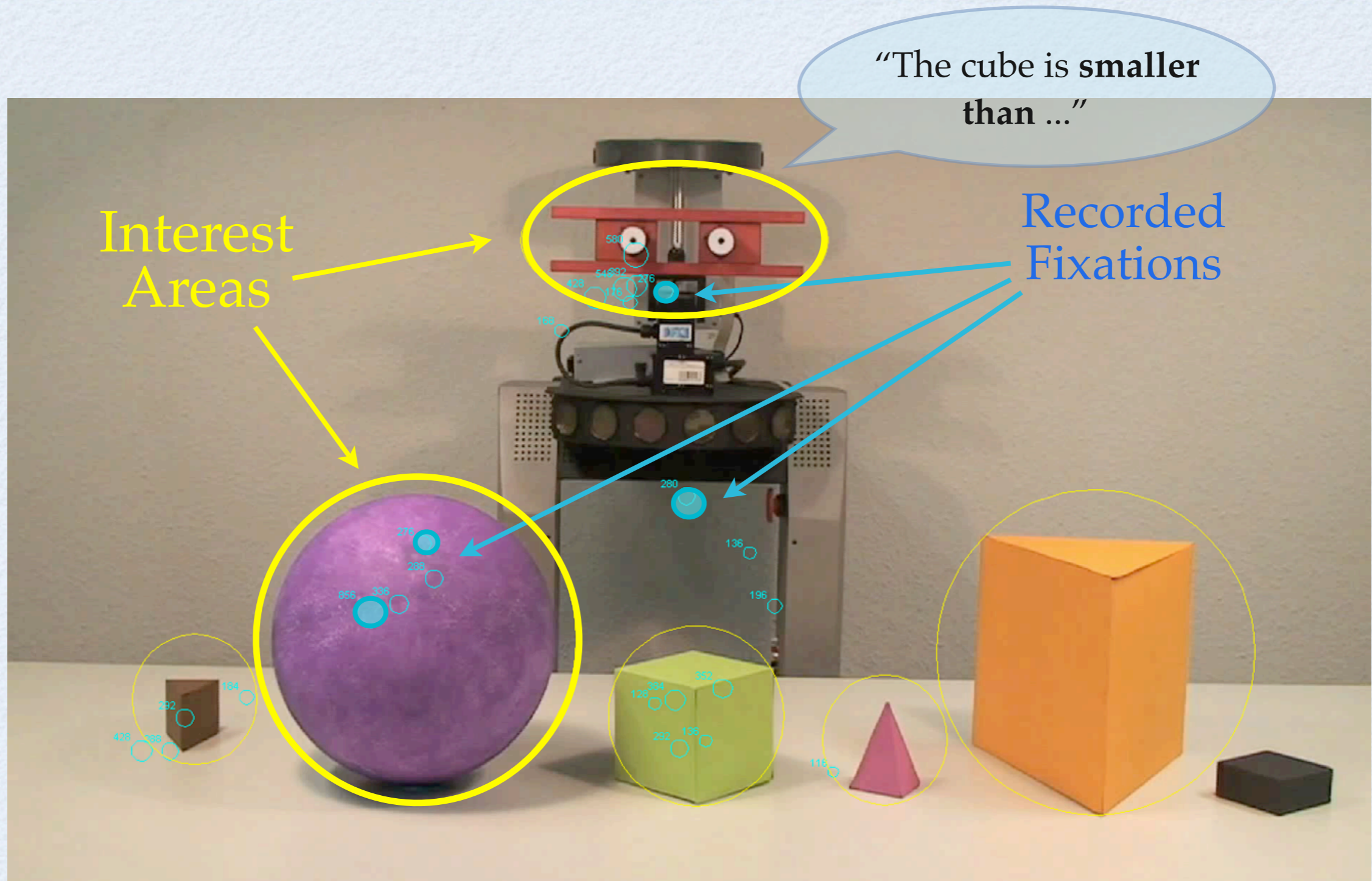
# IA, IP & FIXATIONS



# IA, IP & FIXATIONS

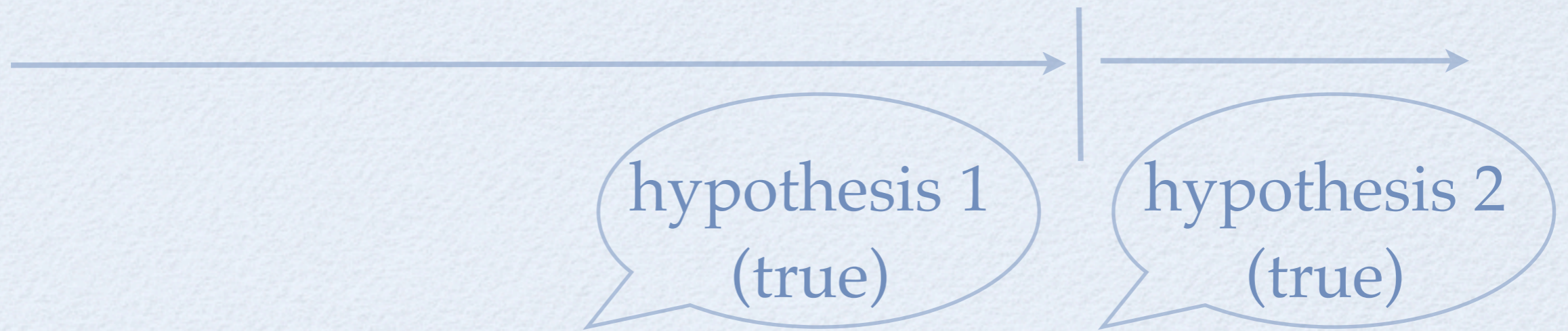


# IA, IP & FIXATIONS



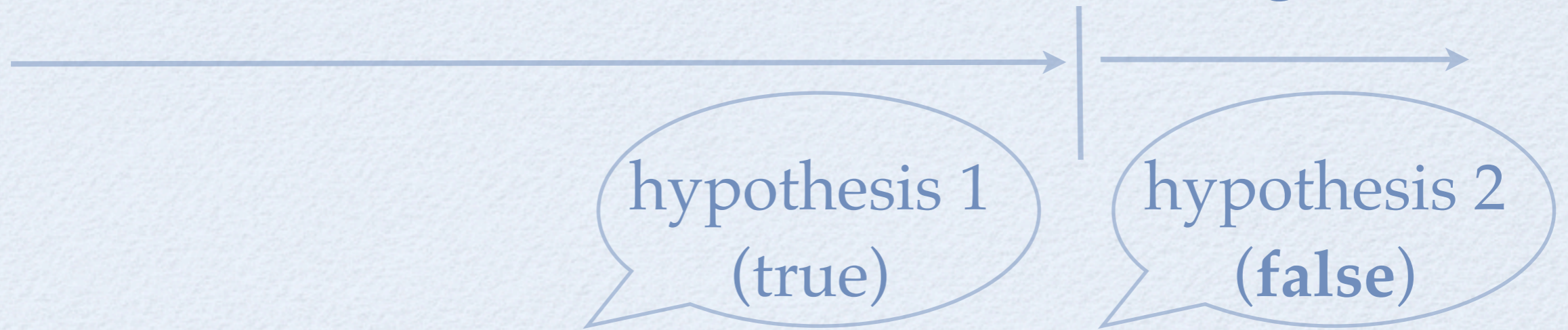
# PREDICTIONS

“The cone is taller than the heart that’s silver.”



# PREDICTIONS

“The cone is taller than the heart that’s **green**.”



# PREDICTIONS

# PREDICTIONS

- Response Times:

# PREDICTIONS

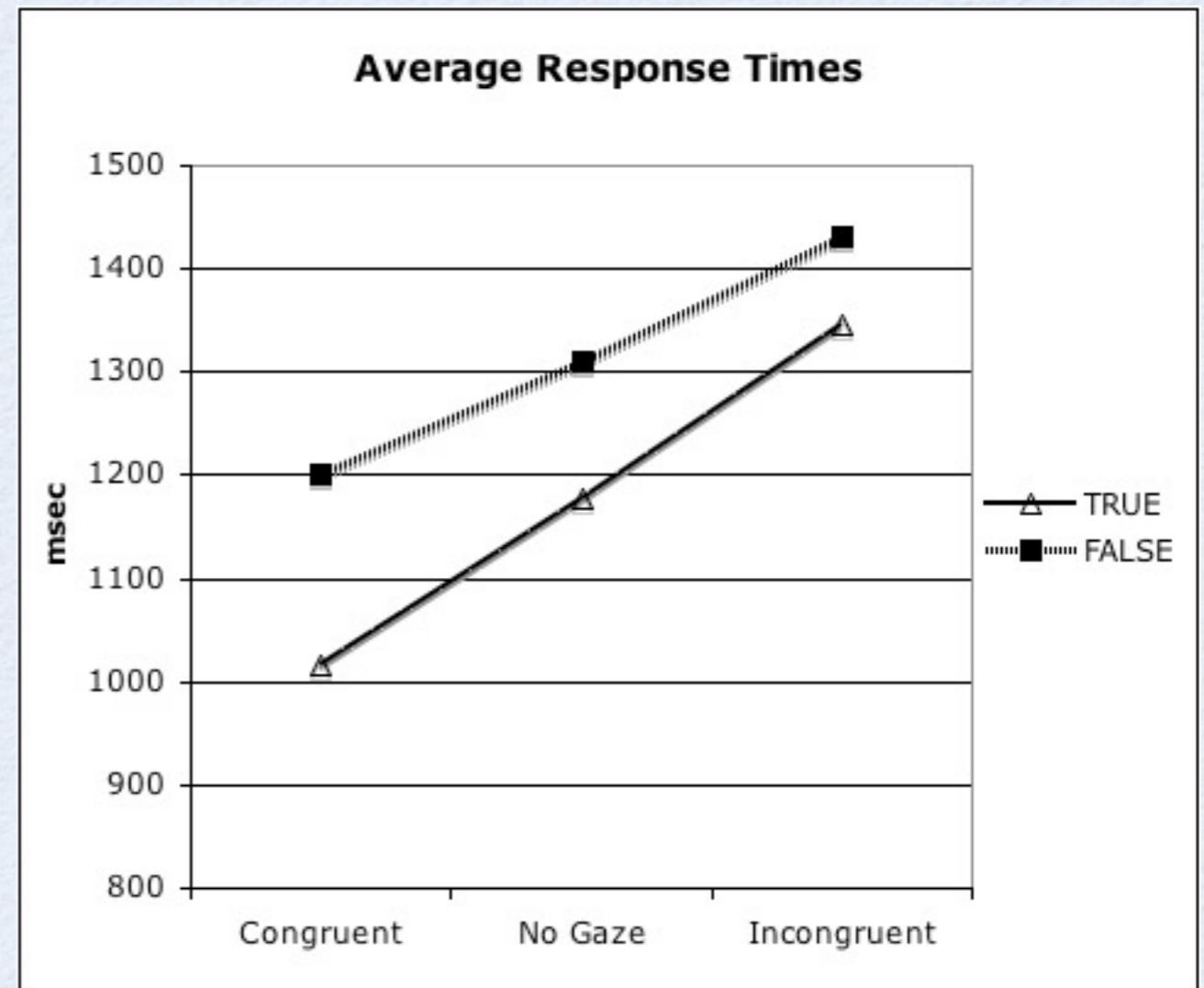
- Response Times:
  - true < false

# PREDICTIONS

- Response Times:
  - true < false
  - congruent < no gaze < incongruent

# RESULTS - EXPERIMENT 2

- Response Times:
  - true statement = shorter RT
  - congruent < no gaze < incongruent
  - tc = fastest



# RESULTS - EXPERIMENT 2

# RESULTS - EXPERIMENT 2

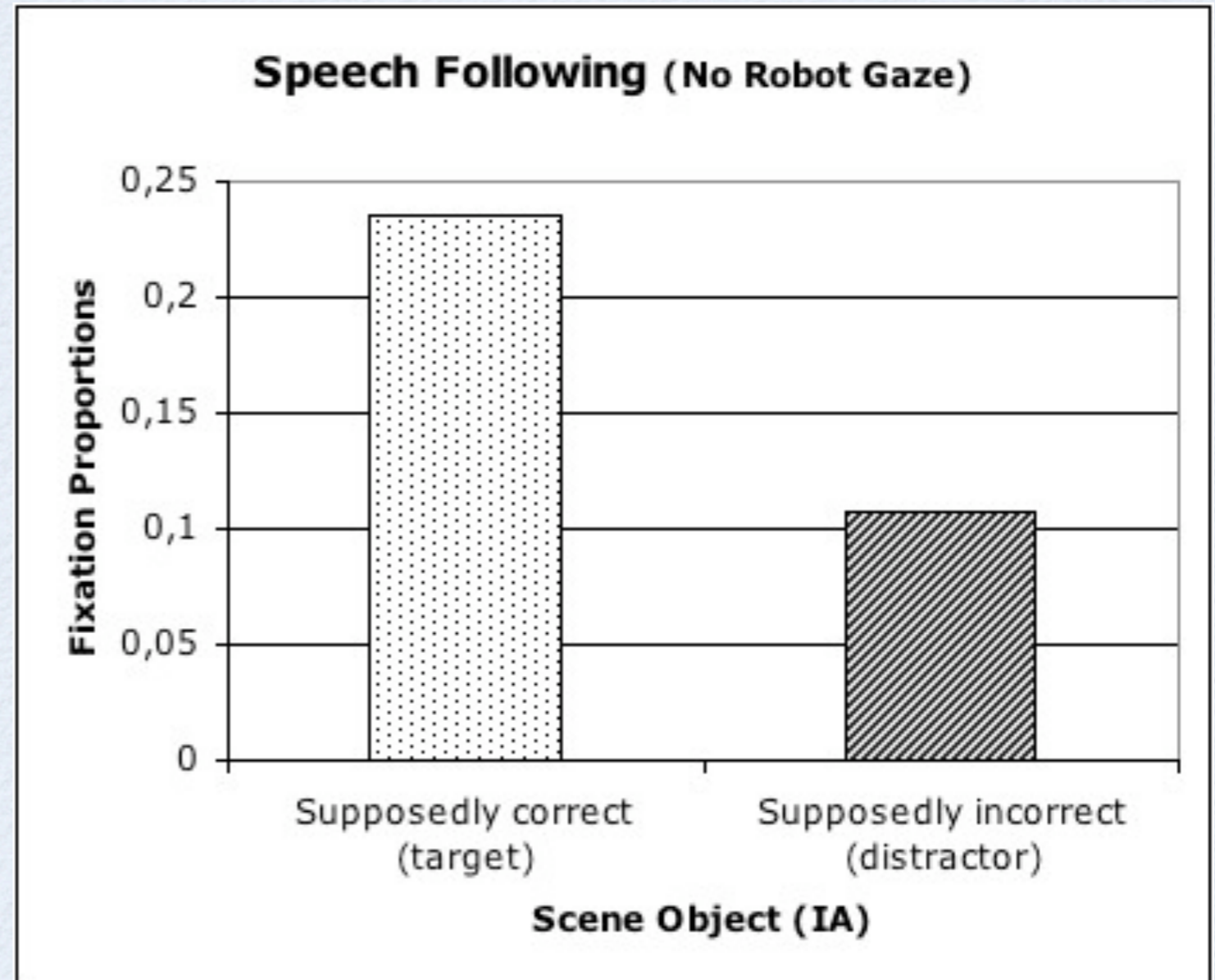
- Fixations

# RESULTS - EXPERIMENT 2

- Fixations
  - Utterance-driven gaze

# RESULTS - EXPERIMENT 2

- Fixations
- Utterance-driven gaze



# RESULTS - EXPERIMENT 2

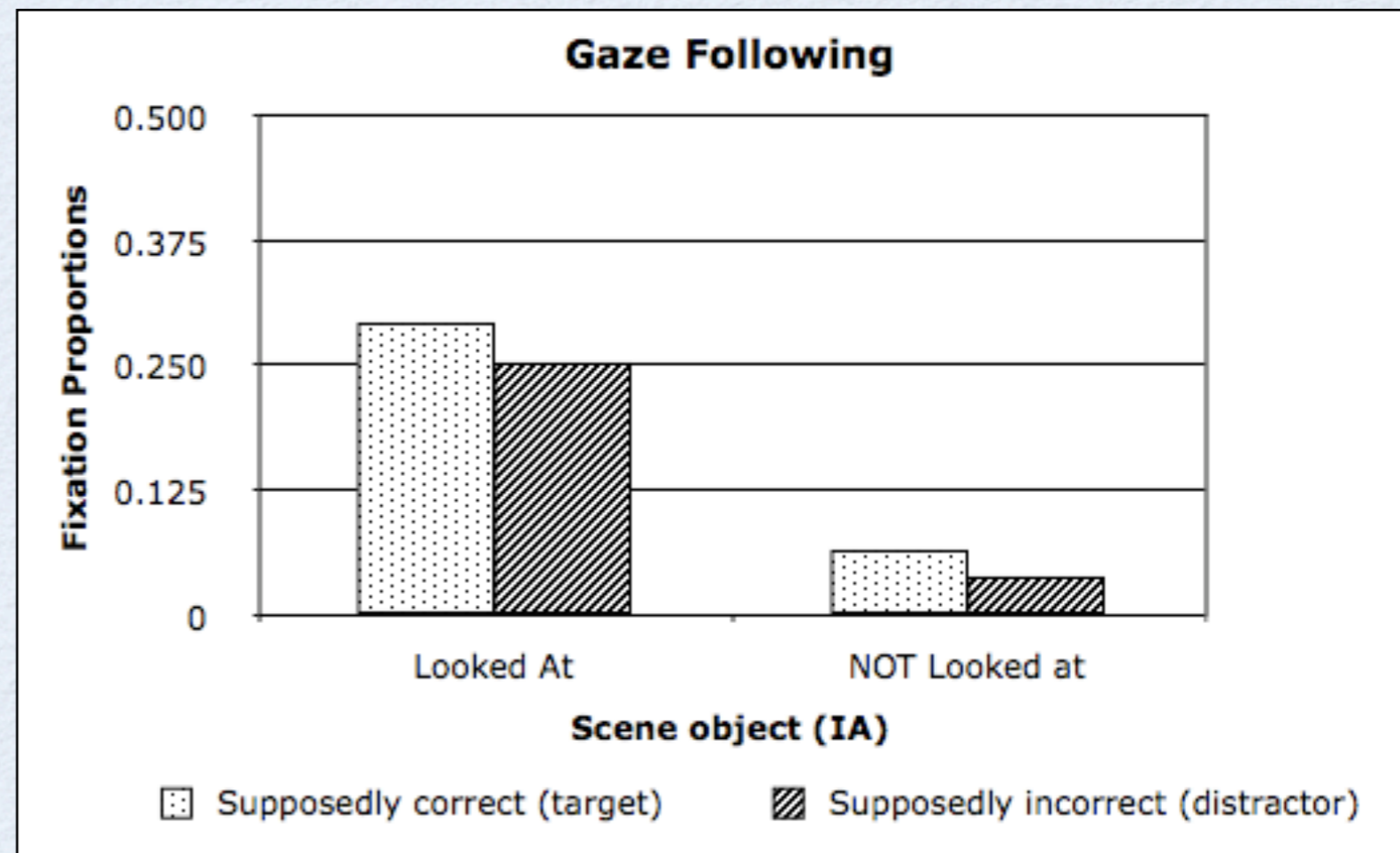
- Fixations
  - Utterance-driven gaze

# RESULTS - EXPERIMENT 2

- Fixations
  - Utterance-driven gaze
  - Joint attention

# RESULTS - EXPERIMENT 2

- Fixations
- Utterance-driven gaze
- Joint attention



# CONCLUSIONS

- HRI behaviour is consistent with behaviour observed in HHI
  - Utterance-mediated gaze & joint attention
- Trust in robot capabilities, belief that robot gaze expresses visual attention of robot
- Robot gaze can be useful and can be irritating
- Robot should use its gaze with caution!