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# Collaborative Problem Solving

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Seminar: Advanced dialogue modeling for practical applications

# Outline

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- ▶ Background
  - ◆ Understanding of terms and assumptions
- ▶ Model
  - ◆ Problem Solving
  - ◆ Collaborative Problem Solving
- ▶ Applications
  - ◆ A sample architecture (TRIPS)
  - ◆ Some sample rules (Sammy)

# Articles

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- ▶ Nate Blaylock, James Allen, and George Ferguson  
Managing communicative intentions with collaborative problem solving (2003)
- ▶ Nate Blaylock  
Towards flexible, domain-independent dialogue management using collaborative problem solving (2007)
- ▶ James Allen, Donna Byron, Myroslava Dzikovska, George Ferguson, Lucian Galescu, and Amanda Stent  
Towards Conversational Human-Computer Interaction (2001)

# Collaborative Problem Solving

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- ▶ The process of agents jointly choosing goals, planning and acting in order to accomplish them.
- ▶ No single-agent decisions possible
- ▶ Model the range between system-control and user control



# Assumptions

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- ▶ Practical Dialogue Hypothesis
  - ◆ The conversational competence required for practical dialogues, while still complex, is significantly simpler to achieve than general human conversational competence.
- ▶ Domain Independence Hypothesis
  - ◆ Within the genre of practical dialogue, the bulk of the complexity in the language interpretation and dialogue management is independent of the task being performed.

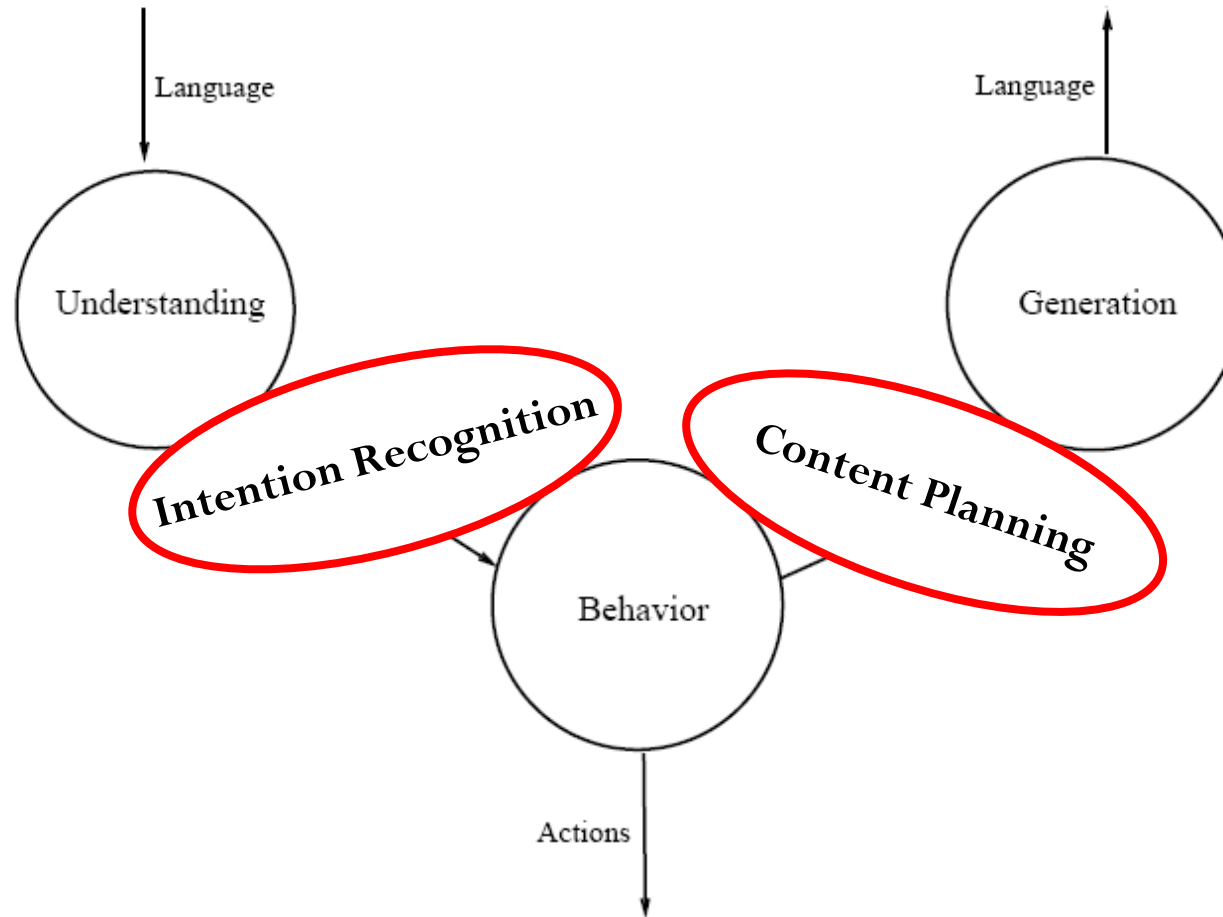
# Goals

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- ▶ Domain Portability
- ▶ Abstracting from linguistic surface
- ▶ Create Intention/Language Interface
  - ◆ Intention Recognition
  - ◆ Content planning
- ▶ Collaboration in planning *and* acting

# Building Conversational Agents

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# Abstract Objects

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- ▶ Objectives
- ▶ Recipes / Solutions
- ▶ Resources
- ▶ Situations
- ▶ Atomic Actions
- ▶ (Evaluations)
- ▶ (Constraints)



# Task Model

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- ▶ A task model provides domain-specific instantiations for the abstract objects
  - ◆ Implemented as typed feature structures
  - ◆ All objects descend from the abstract types
- ▶ The problem solving methods are domain-independent

# Single Agent Problem Solving (PS)

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- ▶ Determining Objectives
  - ◆ What is the goal?
- ▶ Determining and Instantiating Recipes for Objectives
  - ◆ How can it be achieved?
- ▶ Executing Recipes and Monitoring Success
  - ◆ Acting and Reporting

# Commitment Acts

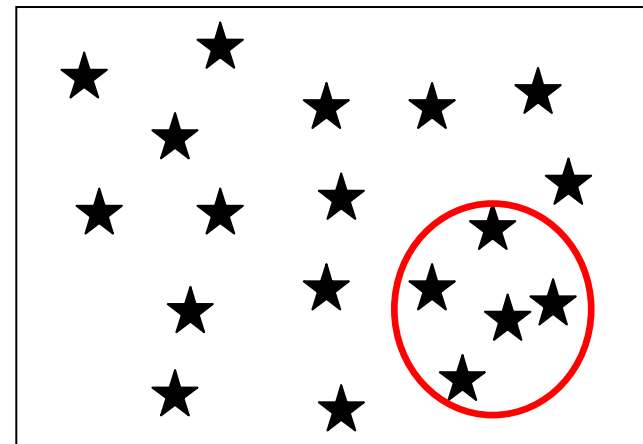
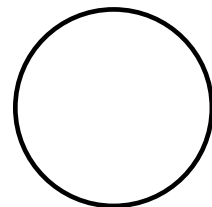
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- ▶ Adopt
- ▶ Select
- ▶ Defer
- ▶ Abandon
- ▶ Release

# Commitment Acts

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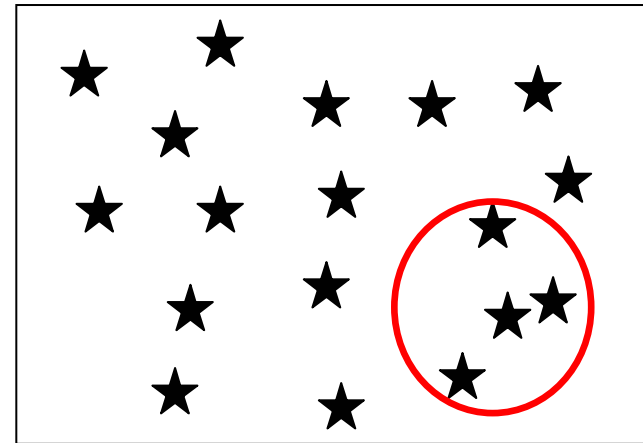
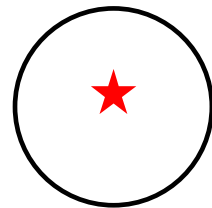
- ▶ Adopt
- ▶ Select
- ▶ Defer
- ▶ Abandon
- ▶ Release



# Commitment Acts

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- ▶ Adopt
- ▶ Select
- ▶ Defer
- ▶ Abandon
- ▶ Release



# Application of Commitment Acts

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	Adopt	Select	Defer	Abandon	Release
Objective	X	X	X	X	X
Recipe	X			X	X
Action	X	X	X	X	X
Resource	X			X	X
Situation	X			X	

# Reasoning Acts

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- ▶ Identify
  - ◆ Which options are available?
- ▶ Evaluate
  - ◆ Which options make sense?
- ▶ Modify
  - ◆ Any parameters have to be changed?

# Application of Reasoning Acts

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	Identify	Evaluate	Modify
Objective	X	X	X
Recipe	X	X	X
Action	X	X	X
Resource	X	X	
Situation	X	X	X



# Collaborative Problem Solving (CPS)

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- ▶ Same Acts as in single agent PS
  - ◆ c-adopt, c-select, c-defer,...
  - ◆ c-identify, c-evaluate
- ▶ Can only be performed after interaction
- ▶ Cooperation and Coordination of both agents
- ▶ Different grades of collaboration

# Interaction Acts

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- ▶ Initiate
- ▶ Continue
- ▶ Complete
- ▶ Reject
  
- ▶ Take CPS-acts as argument
  - ◆ **(initiate (c-adopt (objective (rescue person1))))**

# Dialogue Types

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- ▶ Planning
- ▶ Acting
- ▶ Interleaved Planning and Acting
- ▶ Rejection
- ▶ Negotiation

# Interleaved Planning and Acting

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User: **Send ambulance one to Parma right away.**

(initiate (c-adopt (action (send amb1 Parma))))

(initiate (c-select (action (send amb1 Parma))))

System: **OK.** [sends ambulance] **Acting!**

(complete (c-adopt (action (send amb1 Parma))))

(complete (c-select (action (send amb1 Parma))))

System: **Where should we take the victim once we pick them up?**

(initiate (c-adopt (resource (hospital ?x))))

User: **Rochester General Hospital.**

(continue (c-adopt (resource (hospital RocGen))))

System: **OK.**

(complete (c-adopt (resource (hospital RocGen))))

# Negotiation

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User: **Let's use Ambulance one.**

(initiate (c-adopt (resource (amb1))))

System: **Ambulance one is too far away.**

(reject (c-adopt (resource (amb1))))

(initiate (c-evaluate (resource (amb1) bad too-far)))

System: **Ambulance two is closer.**

(initiate (c-evaluate (resource (amb2) good closer)))

System: **Let's use it.**

(initiate (c-adopt (resource (amb2))))

User: **OK, we'll do that instead.**

(complete (c-evaluate (resource (amb2) good closer)))

(complete (c-evaluate (resource (amb1) bad too-far)))

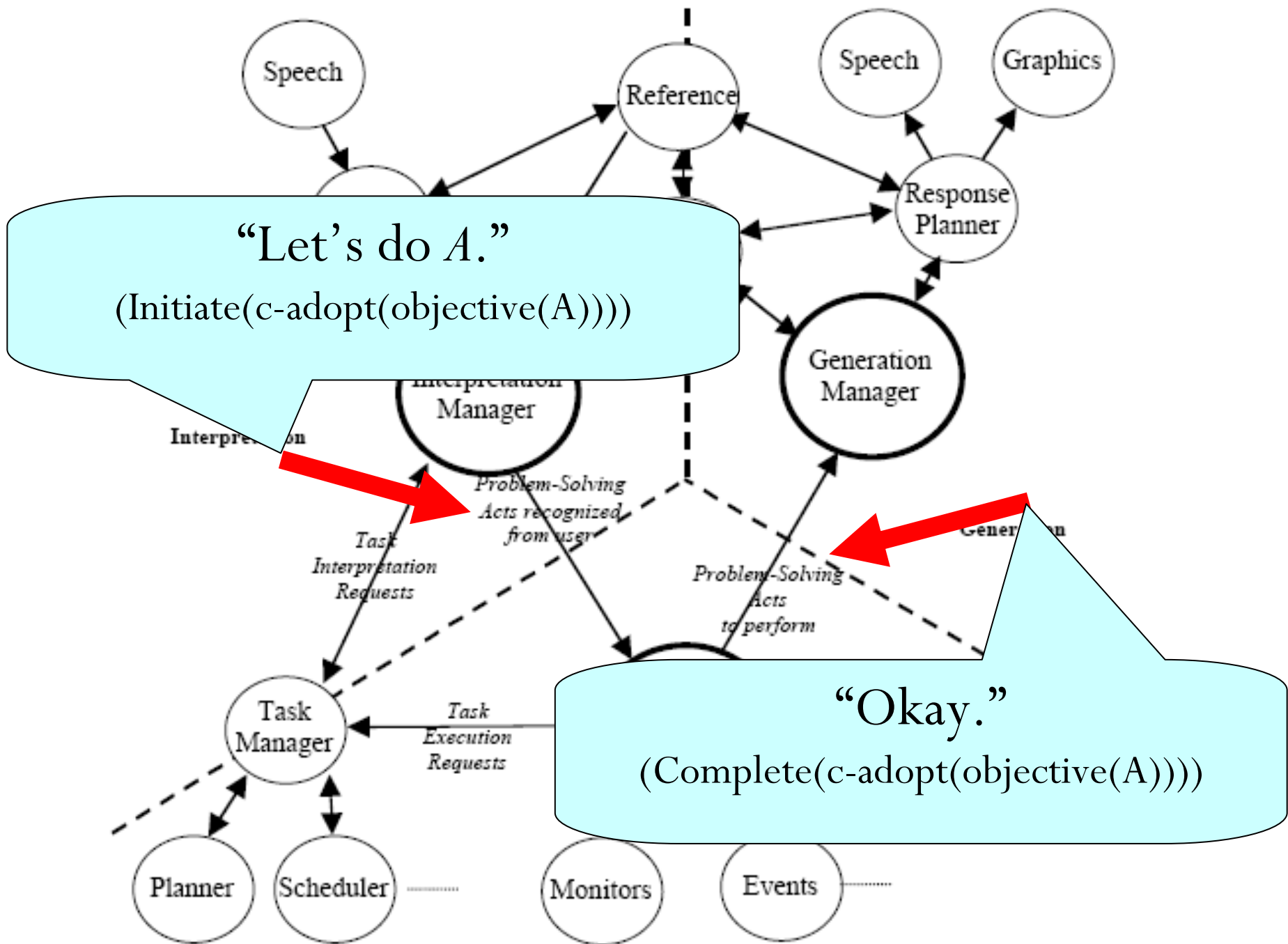
(complete (c-adopt (resource (amb2))))

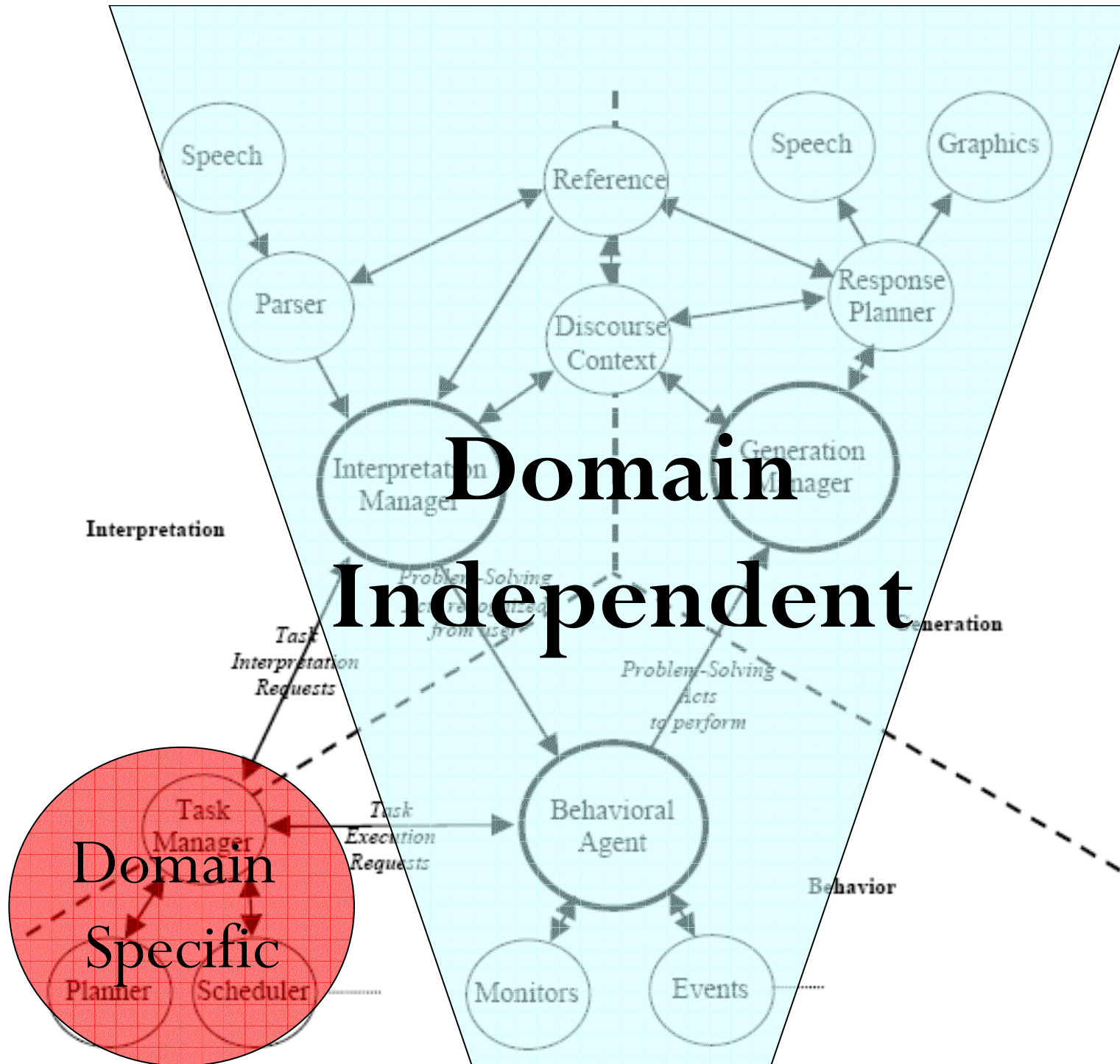
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# TRIPS

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- ▶ The Rochester Interactive Planning System
- ▶ Intelligent Planning Assistant
- ▶ Architecture implements CPS methods







# SAMMIE-05

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- ▶ Multimodal dialogue system for MP3-player control
- ▶ Collaboration only in slot-filling
- ▶ Part of TALK-project

# Domain-independent rules

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IF  $(\textit{initiate}(\textit{c-identify}(\textit{resource}(x))))$

AND  $\textit{resource } A \textit{ can be uniquely identified}$

THEN  $(\textit{continue}(\textit{c-identify}(\textit{resource}(A))))$

- ▶ U: Which Beatles album do you have?

$(\textit{initiate}....$

- ▶ S: I have “Magical Mystery Tour”.

$(\textit{continue}...$

# Domain-independent rules

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IF (*complete(c-select(objective(A))))*)

THEN *put A on internal stack for execution*

- ▶ U: Play “Happy Birthday”!
- ▶ S: OK. (*complete(.....*
- ▶ *Execute?*

# Using domain-specific knowledge

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- ▶ Invoke grounded recipe
  - ◆ Points to object methods
- ▶ Some domain-specific rules necessary
  - ◆ Execution actions which return value
  - ◆ e.g. Create playlist

# Questions?

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- ▶ Considering human as agent (Fabian)
- ▶ Choice of Objects (Miro)
- ▶ Domain-Portability (Alexander, Zhenghan)
- ▶ Modifying a completed CPS-act (Faisal)
  - ◆ initiate(abandon(resource((RH))))/initiate(adopt...(NYH))
  - ◆ initiate(modify....
- ▶ External knowledge in rule formulation (Elahi)
- ▶ State-of-the-art? (Milos)
- ▶ Differences to SharedPlans (Raveesh)



# Thank you!

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[TRIPS demo video](#)



*Conversational Interaction and Spoken Dialogue  
Research Group*