Foundations of Language Science and Technology

Technological Foundations II

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Overview

- > Language Technologies vs Human Language Processing
- > Evaluation Techniques
- > Exploring the LT World

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Performance Revisited **Competence / Performance** ☐ Competence: skills and abilities needed to solve a problem. Cannot be observed directly. ☐ Performance: behaviour in solving a problem. Can be observed. **Applied to Language** ☐ People know a grammar of English. This is their **competence**. ☐ People produce utterances. This is their **performance**. ☐ Different people show different performance. ☐ Their utterances may be deviant or ungrammatical (possibly, this is due to a performance-competence mismatch). LT systems ☐ No distinction between competence and performance. ☐ However, a system's performance usually differs in specific ways from human performance when given the same task. Foundations of Language Science and Technology © 2014 DFKI GmbH

Human and Machine Performance: Out-of-Domain Talk

Assume a two-party dialogue application.

USR is a human customer in an automated travel agency.

SYS is a consultation system for travel recommendations.

After some talk...

USR I'd like one of the smaller hotels, with a pool. I'm a nonswimmer.

SYS You may wish to stay at the BelAir. They have both an indoor and a large outdoor pool.

USR Are these pools deep?

SYS ?? ... ??

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Human and Machine Performance: Out-of-Domain Talk ☐ Out of domain talk may lead to disrupture ☐ System doesn't know the concept of a pool's depth. It doesn't have data about pool depth either. It can't reason about this situation. At most: "I don't know what you mean by a pool being deep." ☐ A human agent should be able to explain, infer and cooperate: "I don't know how deep they are. But the hotel has wading pools, too. So you'll most certainly find a safe area in the water."

Huma	n and Machine Performance: Avoiding Errors
solution". Ex.: style used in foreign lan ☐ Speaker should like to sa ☐ Speaker preverbal mess ☐ Speaker realizes that "pi	ay: "improve the public image of LT" age: "improve the public picture of LT" cture" is the wrong word taphor at all, replans and utters: "create
LT systems don't usually have a dedicated mechanism for error anticipation and avoidance. □ LT errors from basic methods or component technologies show in the output, or emergency measures are taken ("Can you rephrase,	
please?") □ No feedback architecture allowing inter-component interaction	
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What is Language Understanding? Understanding "understanding": Verifiable Scenario in which an actor demonstrates an intellectual effort that involves reasonable action (verbal or nonverbal) as a consequence of a linguistic stimulus There are different ways to define "language understanding", e.g.; ☐ A tourist is satisfied with a trip that has been recommended by a computer agent in the course of a NL dialogue. ☐ An agent correctly translates a text from one language into another ☐ A user constructs an electric circuit based on NL advice provided by a computer assistant. ☐ A robot seeks, finds and fetches a book after being told "to bring it". What language understanding is not: ☐ Successful runs of a parser that maps text input onto a logical form output (no reasonable action) ☐ Phone routing systems (predefined interpretations of digits) ☐ Airport flight information (predefined utterances) Foundations of Language Science and Technology © 2014 DFKI GmbH

Modeling Language Understanding is Always Partial Linguistic coverage ☐ I'd like to fly to Cuba. ☐ Are there still flights to Cuba? ☐ Can you please book me to Havanna. ... In constructing a model we Conceptual (out of domain) coverage necessarily exclude anything ☐ With BA, food is better. that is not modeled ☐ I have fear of flying. Constructing models is not the ☐ Why not by car? right way to making computer □ ... performance more similar to human performance Social coverage (adolescence) ☐ No social learning Adding models of thought, ☐ No social experience behavior, social roles etc. will ☐ No social integration improve performance, but still remain deficient

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Situated Interaction: Evolving Functionality	
Humans learn language in context – they see, smell, feel, think and speak simultaneously.	
A human-like – more holistic – view of a computer acquiring human language is based on <i>situated interaction</i> :	
☐ explore environment with laser scanner, various sensors	
☐ represent perceived objects in a knowledge space (ontology)	
☐ spatial recognition (shape, size, color – " must be a cup")	
 understand the concept of space and reason about it ("I see a sofa, so probably I'm in the living room") 	
□ learn (generalize) from linguistic interaction ("This is a cup!"), annotate ontology with linguistic terms	
☐ understand and generate refererring expressions ("the large blue cup")	
The talking robots group at DFKI is building cognitive robots	
http://talkingrobots.dfki.de	
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Evaluation Techniques I How can we assess whether our technology lives up to expectations? How can we compare a technology with other technologies that do the same thing? Glassbox evaluation (competence predicted by theory) vs. Blackbox evaluation (performance of implemented system) 1. Introspection $\hfill\square$ Author of system sits back and checks what is plausible □ Self-evaluation □ No general validity of results 2. Group tests ☐ A group of possible intended users (= hire a few motivated undergraduates) is testing the system and/or answering questionnaires ☐ Slow, costly, difficult to get reliable results ☐ General validity questionable Foundations of Language Science and Technology

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