

## 1 Type theory: Lexicon

- (a) Proper names:  
 $\text{John} \Rightarrow \lambda F.F(j^*)$
- (b) Determiners:  
 $\text{every} \Rightarrow \lambda F \lambda G \forall x.(F(x) \rightarrow G(x))$   
 $\text{a} \Rightarrow \lambda F \lambda G \exists x.(F(x) \wedge G(x))$   
 $\text{no} \Rightarrow \lambda F \lambda G \neg \exists x.(F(x) \wedge G(x))$
- (c) Most content words are simply analysed as constants (note: transitive verbs get type  $\langle\langle e, t \rangle, t \rangle, \langle e, t \rangle\rangle$ ). But sometimes, the semantics of a word can be represented more precisely by a complex term, e.g.
- $\text{edible} \Rightarrow \lambda P \lambda x.P(x) \wedge \Diamond \exists y.\text{eat}^*(x)(y)$
  - $\text{unmarried} \Rightarrow \lambda P \lambda x.P(x) \wedge \neg \exists y.\text{is\_married\_to}'(y)(x)$

## 2 Modal Logic

Terms:

$$\begin{aligned} \llbracket x \rrbracket^{M,g,w,t} &= g(x) && \text{if } x \text{ is a variable} \\ \llbracket a \rrbracket^{M,g,w,t} &= V_M(a) && \text{if } a \text{ is a constant.} \end{aligned}$$

Formulas:

$$\begin{aligned} \llbracket R(t_1, \dots, t_n) \rrbracket^{M,g,w,t} &= 1 && \text{iff } \langle \llbracket t_1 \rrbracket^{M,g,w,t}, \dots, \llbracket t_n \rrbracket^{M,g,w,t} \rangle \in V_M(R)(w, t) \\ \llbracket t_1 = t_2 \rrbracket^{M,g,w,t} &= 1 && \text{iff } \llbracket t_1 \rrbracket^{M,g,w,t} = \llbracket t_2 \rrbracket^{M,g,w,t} \\ \llbracket \neg \varphi \rrbracket^{M,g,w,t} &= 1 && \text{iff } \llbracket \varphi \rrbracket^{M,g,w,t} = 0 \\ \llbracket \varphi \wedge \psi \rrbracket^{M,g,w,t} &= 1 && \text{iff } \llbracket \varphi \rrbracket^{M,g,w,t} = 1 \text{ and } \llbracket \psi \rrbracket^{M,g,w,t} = 1 \\ \llbracket \varphi \vee \psi \rrbracket^{M,g,w,t} &= 1 && \text{iff } \llbracket \varphi \rrbracket^{M,g,w,t} = 1 \text{ or } \llbracket \psi \rrbracket^{M,g,w,t} = 1 \\ \llbracket \exists x \varphi \rrbracket^{M,g,w,t} &= 1 && \text{iff there is } a \in U_M, \llbracket \varphi \rrbracket^{M,g[x/a],w,t} = 1 \\ \llbracket \forall x \varphi \rrbracket^{M,g,w,t} &= 1 && \text{iff for all } a \in U_M, \llbracket \varphi \rrbracket^{M,g[x/a],w,t} = 1 \\ \llbracket \Box \varphi \rrbracket^{M,g,w,t} &= 1 && \text{iff for all } w' \in W, \llbracket \varphi \rrbracket^{M,g,w',t} = 1 \\ \llbracket \Diamond \varphi \rrbracket^{M,g,w,t} &= 1 && \text{iff there is } w' \in W, \llbracket \varphi \rrbracket^{M,g,w',t} = 1 \\ \llbracket \mathbf{F} \varphi \rrbracket^{M,g,w,t} &= 1 && \text{iff there is } t' > t, \llbracket \varphi \rrbracket^{M,g,w,t'} = 1 \\ \llbracket \mathbf{G} \varphi \rrbracket^{M,g,w,t} &= 1 && \text{iff for all } t' > t, \llbracket \varphi \rrbracket^{M,g,w,t'} = 1 \\ \llbracket \mathbf{P} \varphi \rrbracket^{M,g,w,t} &= 1 && \text{iff there is } t' < t, \llbracket \varphi \rrbracket^{M,g,w,t'} = 1 \\ \llbracket \mathbf{H} \varphi \rrbracket^{M,g,w,t} &= 1 && \text{iff for all } t' < t, \llbracket \varphi \rrbracket^{M,g,w,t'} = 1 \end{aligned}$$

### 3 Nested Cooper Storage

Transitive verbs are analysed as constants of type  $\langle\langle e, t \rangle, t \rangle, \langle e, t \rangle$ .

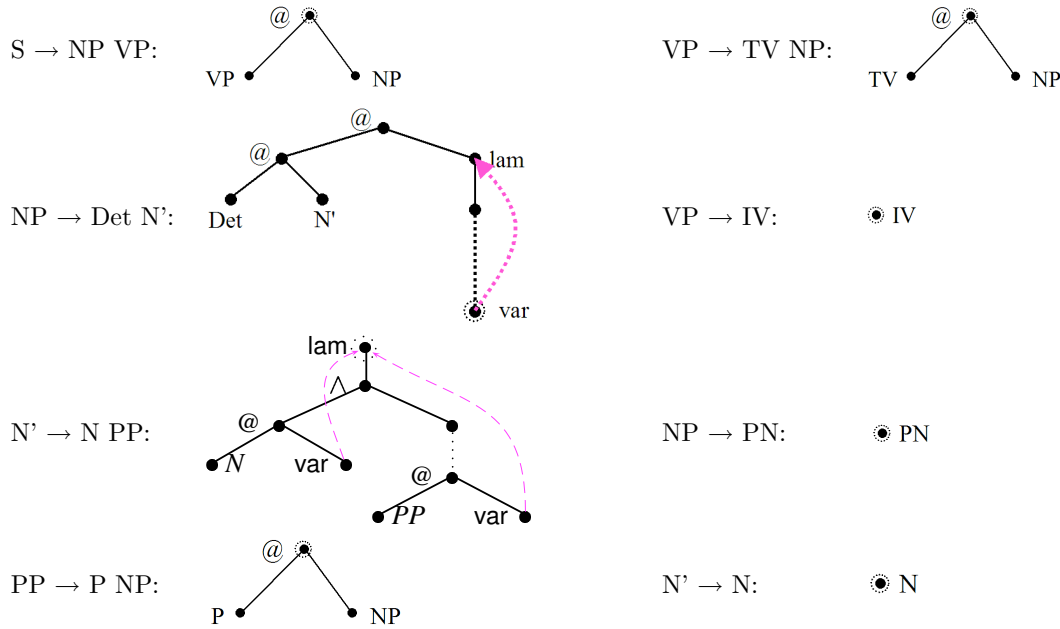
(a) Storage:

$$\frac{B \Rightarrow \langle \gamma, \Gamma \rangle \quad B \text{ is an NP node}}{B \Rightarrow \langle \lambda P.P(x_i), \{\langle \gamma, \Gamma \rangle_i\} \rangle \quad i \in \mathbf{N} \text{ is a new index}}$$

(b) Retrieval:

$$\frac{A \Rightarrow \langle \alpha, \Delta \cup \{\langle \gamma, \Gamma \rangle_i\} \rangle \quad A \text{ is any sentence node}}{A \Rightarrow \langle \gamma(\lambda x_i.\alpha), \Delta \cup \Gamma \rangle}$$

### 4 Dominance graphs: Semantics construction



### 5 Dominance graphs: Solving

The three rules of the dominance graph solver:

- Choice*: If a node  $u$  has two dominance parents  $v$  and  $w$ , generate two new dominance graphs containing the edges  $(v, w)$  and  $(w, v)$ , and continue the search for solved forms for both new graphs.
- Parent Normalisation*: If  $(u, v)$  is a dominance edge, and  $v$  has a father  $w$  over a tree edge, replace  $(u, v)$  by  $(u, w)$ .
- Redundancy Elimination*: If  $e = (u, v)$  is an edge and there is a path from  $u$  to  $v$  that doesn't use  $e$ , delete  $e$  from the dominance graph.

## 6 DRT: Syntax and Semantics

A discourse representation structure (DRS)  $K$  is a pair  $\langle U_K, C_K \rangle$  where

- $U_K$  is a set of discourse referents
- $C_K$  is a set of conditions.

Conditions:

$R(u_1, \dots, u_n)$	$R$ is an $n$ -place relation, $u_i \in U_K$
$u = v$	$u, v \in U_K$
$u = a$	$u \in U_K$ , $a$ a proper name
$K_1 \Rightarrow K_2$	$K_1$ and $K_2$ DRSs
$K_1 \vee K_2$	$K_1$ and $K_2$ DRSs
$\neg K_1$	$K_1$ is a DRS

## 7 DRT: Embedding, verifying embedding

Let  $U_D$  be a set of discourse referents,  $K = \langle U_K, C_K \rangle$  a DRS with  $U_K \subseteq U_D$ ,  $M = \langle U_M, V_M \rangle$  a model structure of first-order predicate logic that is suitable for  $K$ . An *embedding* of  $U_D$  into  $M$  is a (partial) function that assigns individuals from  $U_M$  to discourse referents.

An embedding  $f$  *verifies* the DRS  $K$  in  $M$  ( $f \models_M K$ ) iff

- (a)  $U_K \subseteq \text{Dom}(f)$  and
- (b)  $f$  verifies each condition  $\alpha \in C_K$ .

$f$  verifies a condition  $\alpha$  in  $M$  ( $f \models_M \alpha$ ) in the following cases:

$f \models_M R(u_1, \dots, u_n)$	iff $\langle f(u_1), \dots, f(u_n) \rangle \in V_M(R)$
$f \models_M u = v$	iff $f(u) = f(v)$
$f \models_M u = a$	iff $f(u) = V_M(a)$
$f \models_M K_1 \Rightarrow K_2$	iff for all $g \supseteq_{U_{K_1}} f$ such that $g \models_M K_1$ , there is $h \supseteq_{U_{K_2}} g$ such that $h \models_M K_2$
$f \models_M \neg K_1$	iff there is no $g \supseteq_{U_{K_1}} f$ such that $g \models_M K_1$
$f \models_M K_1 \vee K_2$	iff there is a $g_1 \supseteq_{U_{K_1}} f$ such that $g_1 \models_M K_1$ , or there is a $g_2 \supseteq_{U_{K_2}} f$ such that $g_2 \models_M K_2$ .

## 8 Presuppositions (van der Sandt)

A proto-DRS is a triple  $\langle U_K, C_K, A_K \rangle$ , where

- $U_K$  is a set of discourse referents
- $C_K$  is a set of conditions
- $A_K$  is a set of “anaphoric” (alpha-) DRSs.

## 9 Resolution of $\alpha$ -DRSs

Let  $K$  and  $K'$  be proto-DRSs such that  $K'$  is a sub-DRS of  $K$ . Let  $\gamma = \alpha x K_s$  be an alpha-free alpha-DRS in  $K'$ , and let  $K_t$  be a sub-DRS of  $K$  that is accessible for  $\gamma$ .

- (a) Accommodation: Remove  $\gamma$  from  $K'$ , and extend  $K_t$  with  $U_{K_s}$  and  $C_{K_s}$ .
- (b) Binding: Let further  $y \in U_{K_t}$  be a discourse referent that is suitable for  $\gamma$ . Then remove  $\gamma$  from  $K'$ , and extend  $K_t$  with  $U_{K_s}$  and  $C_{K_s}$  and the condition  $x = y$ .

## 10 DPL: Interpretation

Terms:

$$\begin{aligned} \llbracket x \rrbracket^{M,h} &= h(x) && \text{if } x \text{ is a variable} \\ \llbracket a \rrbracket^{M,h} &= V_M(a) && \text{if } a \text{ is a constant.} \end{aligned}$$

Formulas:

$$\begin{aligned} \llbracket R(t_1, \dots, t_n) \rrbracket^M &= \{ \langle g, h \rangle \mid h = g \text{ and } \langle \llbracket t_1 \rrbracket^{M,h}, \dots, \llbracket t_n \rrbracket^{M,h} \rangle \in V_M(R) \} \\ \llbracket t_1 = t_2 \rrbracket^M &= \{ \langle g, h \rangle \mid h = g \text{ and } \llbracket t_1 \rrbracket^{M,h} = \llbracket t_2 \rrbracket^{M,h} \} \\ \llbracket \neg \varphi \rrbracket^M &= \{ \langle g, h \rangle \mid h = g \text{ and ex. no } k \text{ s.t. } \langle g, k \rangle \in \llbracket \varphi \rrbracket^M \} \\ \llbracket \varphi \wedge \psi \rrbracket^M &= \{ \langle g, h \rangle \mid \text{ex. } k \text{ s.t. } \langle g, k \rangle \in \llbracket \varphi \rrbracket^M \text{ and } \langle k, h \rangle \in \llbracket \psi \rrbracket^M \} \\ \llbracket \varphi \vee \psi \rrbracket^M &= \{ \langle g, h \rangle \mid h = g \text{ and ex. } k \text{ s.t. } \langle g, k \rangle \in \llbracket \varphi \rrbracket^M \text{ or } \langle g, k \rangle \in \llbracket \psi \rrbracket^M \} \\ \llbracket \varphi \rightarrow \psi \rrbracket^M &= \{ \langle g, h \rangle \mid h = g \text{ and for all } k: \text{if } \langle g, k \rangle \in \llbracket \varphi \rrbracket^M, \text{ then ex. } j \text{ s.t. } \langle k, j \rangle \in \llbracket \psi \rrbracket^M \} \\ \llbracket \exists x. \varphi \rrbracket^M &= \{ \langle g, h \rangle \mid \text{ex. } k[x]g \text{ s.t. } \langle k, h \rangle \in \llbracket \varphi \rrbracket^M \} \\ \llbracket \forall x. \varphi \rrbracket^M &= \{ \langle g, h \rangle \mid h = g \text{ and for each } k[x]g, \text{ there is an } m \text{ s.t. } \langle k, m \rangle \in \llbracket \varphi \rrbracket^M \} \end{aligned}$$

## 11 DPL: Truth, equivalence, entailment

(a) Truth and validity:

- A formula  $\varphi$  is *true in  $M$  with respect to an input assignment  $g$*  iff there is a  $h$  s.t.  $\langle g, h \rangle \in \llbracket \varphi \rrbracket^M$ .
- A formula  $\varphi$  is *true in  $M$*  iff  $\varphi$  is true in  $M$  with respect to every input assignment.
- $\varphi$  is *valid* iff it is true in every model structure.

(b) Notions of equivalence:

- *Satisfaction set*:  $\backslash \varphi \backslash_M = \{g \mid \text{exists } h \text{ s.t. } \langle g, h \rangle \in \llbracket \varphi \rrbracket^M\}$
- *s-equivalence* (static equivalence):  $\varphi \Leftrightarrow_S \psi$  iff for all  $M$ ,  $\backslash \varphi \backslash_M = \backslash \psi \backslash_M$
- *full equivalence* (dynamic equivalence):  $\varphi \Leftrightarrow \psi$  iff for all  $M$ ,  $\llbracket \varphi \rrbracket^M = \llbracket \psi \rrbracket^M$

(c) Notions of entailment:

- *Static entailment*:  $\varphi \models_S \psi$  iff for all  $M$ ,  $g$ : If  $\varphi$  is true wrt.  $M$  and  $g$ , then  $\psi$  is true wrt.  $M$  and  $g$ .
- *Meaning inclusion*:  $\varphi \leq \psi$  iff  $\llbracket \varphi \rrbracket^M \subseteq \llbracket \psi \rrbracket^M$ .
- *Dynamic entailment*:  $\varphi \models \psi$  iff for all  $M$ ,  $g$ ,  $h$ : if  $\langle g, h \rangle \in \llbracket \varphi \rrbracket^M$ , then there exists  $k$  s.t.  $\langle h, k \rangle \in \llbracket \psi \rrbracket^M$ .