

1 DPL Representations

Consider the sentence (1) with its DPL representation (2).

(1) If Pedro owns a donkey, he beats it.

(2) $(\exists x. \text{donkey}(x) \wedge \text{own}(p^*, x)) \rightarrow \text{beat}(p^*, x)$

(a) Determine the denotation of (2) using the definitions from the lecture. Simplify your result as much as possible.

(b) Consider the following alternative DPL representations of (2).

(3) $(\neg \exists x. (\text{donkey}(x) \wedge \text{own}(p^*, x))) \vee \text{beat}(p^*, x)$

(4) $\forall x. (\text{donkey}(x) \wedge \text{own}(p^*, x) \rightarrow \text{beat}(p^*, x))$

Determine which of (2), (3), and (4) are equivalent or statically equivalent to each other. Explain why you believe in each equivalence or non-equivalence. You can justify your answers either by computing the denotations, or by general considerations.

2 Equivalence

We showed in the lecture that the connectives \vee , \rightarrow , and \forall can be defined in DPL using the connectives \neg , \wedge , and \exists . The converse is false; in particular, none of the following claims of (static) equivalence are true for all formulas φ, ψ .

(a) $\varphi \wedge \psi \Leftrightarrow \neg(\varphi \rightarrow \neg\psi)$

(b) $\varphi \wedge \psi \Leftrightarrow_S \neg(\neg\varphi \vee \neg\psi)$

(c) $\varphi \rightarrow \psi \Leftrightarrow_S \neg\varphi \vee \psi$

(d) $\exists x. \varphi \Leftrightarrow \neg \forall x. \neg\varphi$

Explain why each claim is false, and give formulas for φ and ψ that illustrate this. Feel free to compute denotations where this is useful for you, but you can also argue more generally.

3 Entailment

Determine whether $\varphi \models_S \psi$, $\varphi \leq \psi$, or $\varphi \models \psi$ generally hold if

(a) φ is of the form $\neg A$ and ψ is of the form $\neg\neg\neg A$;

(b) φ is of the form $A \wedge B$ and ψ is of the form A ;

(c) φ is of the form $(A \rightarrow B) \wedge A$ and ψ is of the form B .

Justify your claims, and give examples for each negative claim. Feel free to compute denotations where this is useful for you, but you can also argue more generally.

4 DRT to PL via DPL

In the lectures about DRT, we showed how each DRS and each condition can be translated into a formula of standard predicate logic that is satisfied by the same models using a translation T .

Now put DPL into this picture by doing the following:

- (a) Give a translation T_1 from DRT to DPL with the following properties:
 - T_1 translates a DRS K into a formula $T_1(K)$ such that K and $T_1(K)$ are true in the same models.
 - T_1 translates a condition C into an externally static formula $T_1(C)$ such that C and $T_1(C)$ are true in the same models.
 - T_1 is as simple as possible.
- (b) Give a translation T_2 from DPL to standard predicate logic such that T_2 translates a DPL formula φ into a formula $T_2(\varphi)$ that is true in the same models. It is sufficient to define T_2 on the results of the translation T_1 .
- (c) Argue briefly that for any DRS K , $T(K) = T_2(T_1(K))$.
- (d) * Extend T_2 to a translation T'_2 that works for *all* DPL formulas.

5 * “Static” formulas

The satisfaction set $\backslash\varphi\backslash_M$ of a DPL formula and the set $S_M(\varphi) = \{g \mid \llbracket \varphi \rrbracket^{M,g} = 1\}$ of all satisfying variable assignments of a formula of standard predicate logic are closely related notions. They are identical for many formulas φ – but not for all. For example, the satisfaction set of $\exists x((\exists x.P(x)) \wedge \neg P(x))$ is always empty because this formula is unsatisfiable in DPL. But in some models the set of satisfying variable assignments is non-empty, because the variables in $P(x)$ and $\neg P(x)$ are bound by different quantifiers in standard predicate logic.

Characterise the set of all formulas φ for which $\backslash\varphi\backslash_M = S_M(\varphi)$ for all M .