1 Type theory: Lexicon

- (a) Proper names: John $\Rightarrow \lambda F.F(j^*)$
- (b) Determiners: $\begin{array}{l} \text{every} \Rightarrow \lambda F \lambda G \forall x. (F(x) \to G(x)) \\ \text{a} \Rightarrow \lambda F \lambda G \exists x. (F(x) \land G(x)) \\ \text{no} \Rightarrow \lambda F \lambda G \neg \exists x. (F(x) \land G(x)) \end{array}$
- (c) Most content words are simply analysed as constants (note: transitive verbs get type $\langle \langle \langle e, t \rangle, t \rangle, \langle e, t \rangle \rangle$). But sometimes, the semantics of a word can be represented more precisely by a complex term, e.g.
 - $\text{ edible} \Rightarrow \lambda x \diamond \exists y. \mathsf{eat}^*(x)(y)$
 - unmarried $\Rightarrow \lambda x \neg \exists y. \mathsf{is_married_to'}(y)(x)$

2 Modal Logic

Terms:

 $\llbracket x \rrbracket^{M,g,w,t} = g(x) \quad \text{if } x \text{ is a variable} \\ \llbracket a \rrbracket^{M,g,w,t} = V_M(a) \quad \text{if } a \text{ is a constant.}$

Formulas:

$$\begin{split} & [R(t_1, \dots, t_n)]^{M,g,w,t} = 1 & \text{iff } \langle [t_1]^{M,g,w,t}, \dots, [t_n]^{M,g,w,t} \rangle \in V_M(R)(w,t) \\ & [t_1 = t_2]^{M,g,w,t} = 1 & \text{iff } [t_1]^{M,g,w,t} = [t_2]^{M,g,w,t} \rangle \in V_M(R)(w,t) \\ & [\neg\varphi]^{M,g,w,t} = 1 & \text{iff } [[\varphi]^{M,g,w,t} = 0 \\ & [\varphi \land \psi]^{M,g,w,t} = 1 & \text{iff } [[\varphi]^{M,g,w,t} = 1 & \text{and } [[\psi]]^{M,g,w,t} = 1 \\ & [[\varphi \lor \psi]^{M,g,w,t} = 1 & \text{iff } [[\varphi]^{M,g,w,t} = 1 & \text{or } [[\psi]^{M,g,w,t} = 1 \\ & [\exists x \varphi]^{M,g,w,t} = 1 & \text{iff } there is \ u \in U_M, \ [[\varphi]^{M,g,w,t} = 1 \\ & [\forall x \varphi]^{M,g,w,t} = 1 & \text{iff for all } u \in U_M, \ [[\varphi]^{M,g,w,t} = 1 \\ & [[\varphi \lor]^{M,g,w,t} = 1 & \text{iff there is } w' \in W, \ [[\varphi]^{M,g,w',t} = 1 \\ & [[\varphi \lor]^{M,g,w,t} = 1 & \text{iff there is } t' > t, \ [[\varphi]^{M,g,w,t'} = 1 \\ & [[\varphi \lor]^{M,g,w,t} = 1 & \text{iff for all } t' > t, \ [[\varphi]^{M,g,w,t'} = 1 \\ & [[\varphi \lor]^{M,g,w,t} = 1 & \text{iff there is } t' < t, \ [[\varphi]^{M,g,w,t'} = 1 \\ & [[\varphi \lor]^{M,g,w,t} = 1 & \text{iff for all } t' < t, \ [[\varphi]^{M,g,w,t'} = 1 \\ & [[\varphi \lor]^{M,g,w,t} = 1 & \text{iff for all } t' < t, \ [[\varphi]^{M,g,w,t'} = 1 \\ & [[\varphi \lor]^{M,g,w,t} = 1 & \text{iff for all } t' < t, \ [[\varphi]^{M,g,w,t'} = 1 \\ & [[\varphi \lor]^{M,g,w,t} = 1 & \text{iff for all } t' < t, \ [[\varphi]^{M,g,w,t'} = 1 \\ & [[\varphi \lor]^{M,g,w,t} = 1 & \text{iff for all } t' < t, \ [[\varphi]^{M,g,w,t'} = 1 \\ & [[\varphi \lor]^{M,g,w,t} = 1 & \text{iff for all } t' < t, \ [[\varphi]^{M,g,w,t'} = 1 \\ & [[\varphi \lor]^{M,g,w,t} = 1 & \text{iff for all } t' < t, \ [[\varphi]^{M,g,w,t'} = 1 \\ & [[\varphi \lor]^{M,g,w,t} = 1 & \text{iff for all } t' < t, \ [[\varphi]^{M,g,w,t'} = 1 \\ & [[\varphi \lor]^{M,g,w,t} = 1 & \text{iff for all } t' < t, \ [[\varphi]^{M,g,w,t'} = 1 \\ & [[\varphi \lor]^{M,g,w,t} = 1 & \text{iff for all } t' < t, \ [[\varphi]^{M,g,w,t'} = 1 \\ & [[\varphi \lor]^{M,g,w,t'} = 1 & \text{iff for all } t' < t, \ [[\varphi]^{M,g,w,t'} = 1 \\ & [[\varphi \lor]^{M,g,w,t'} = 1 & \text{iff for all } t' < t, \ [[\varphi]^{M,g,w,t'} = 1 \\ & [[\varphi \lor]^{M,g,w,t'} = 1 & \text{iff for all } t' < t, \ [[\varphi]^{M,g,w,t'} = 1 \\ & [[\varphi \lor]^{M,g,w,t'} = 1 & \text{iff for all } t' < t, \ [[\varphi \lor]^{M,g,w,t'} = 1 \\ & [[\varphi \lor]^{M,g,w,t'} = 1 & \text{iff for all } t' < t, \ [[\varphi \lor]^{M,g,w,t'} = 1 \\ & [[\varphi \lor]^{M,g,w,t'} = 1 & \text{iff for all } t' < t, \ [[\varphi \lor]$$

3 Nested Cooper Storage

Transitive verbs are now analysed as constants of type $\langle e, \langle e, t \rangle \rangle$.

(a) Storage:

$$\begin{array}{cccc} B & \Rightarrow & \langle \gamma, \Gamma \rangle & B \text{ is an NP node} \\ \hline C & \Rightarrow & \langle \beta, \Delta \rangle & \beta \in WE_{\langle e, \tau \rangle} \\ \hline A & \Rightarrow & \langle \beta(x_i), \Delta \cup \{\langle \gamma, \Gamma \rangle_i\} \rangle & i \in \mathbf{N} \text{ is a new index} \end{array}$$

(b) Retrieval:

$$\begin{array}{ccc} A & \Rightarrow & \langle \alpha, \Delta \cup \{ \langle \gamma, \Gamma \rangle_i \} \rangle & A \text{ is any sentence node} \\ \hline A & \Rightarrow & \langle \gamma(\lambda x_i.\alpha), \Delta \cup \Gamma \rangle \end{array}$$

4 Dominance graphs: Semantics construction



5 Dominance graphs: Solving

The three rules of the dominance graph solver:

- (a) Choice: If a node u has two dominance parents v and w, generate two new dominance graphs containing the edges (v, w) and (w, v), and continue the search for solved forms for both new graphs.
- (b) Parent Normalisation: If (u, v) is a dominance edge, and v has a father w over a tree edge, replace (u, v) by (u, w).
- (c) Redundancy Elimination: If e = (u, v) is an edge and there is a path from u to v that doesn't use e, delete e from the dominance graph.

6 DRT: Syntax and Semantics

A discourse representation structure (DRS) K is a pair $\langle U_K, C_K \rangle$ where

 $- U_K$ is a set of discourse referents

 $-C_K$ is a set of conditions.

Conditions:

$R(u_1,\ldots,u_n)$ R is an <i>n</i> -place relation, $u_i \in$	U_K
$u = v$ $u, v \in U_K$	
$u = a$ $u \in U_K, a \text{ a proper name}$	
$K_1 \Rightarrow K_2$ $K_1 \text{ and } K_2 \text{ DRSs}$	
$K_1 \lor K_2$ K_1 and K_2 DRSs	
$\neg K_1$ K ₁ is a DRS	

7 DRT: Embedding, verifying embedding

Let U_D be a set of discourse referents, $K = \langle U_K, C_K \rangle$ a DRS with $U_K \subseteq U_D$, $M = \langle U_M, V_M \rangle$ a model structure of first-order predicate logic that is suitable for K. An *embedding* of U_D into M is a (partial) function that assigns individuals from U_M to discourse referents.

An embedding f verifies the DRS K in M $(f \models_M K)$ iff

- (a) $U_K \subseteq \text{Dom}(f)$ and
- (b) f verifies each condition $\alpha \in C_K$.

f verifies a condition α in M (f \models_M \alpha) in the following cases:

$f \models_M R(u_1, \ldots, u_n)$	iff $\langle f(u_1), \ldots, f(u_n) \rangle \in V_M(R)$
$f \models_M u = v$	$\inf f(u) = f(v)$
$f \models_M u = a$	$\text{iff } f(u) = V_M(a)$
$f\models_M K_1 \Rightarrow K_2$	iff for all $g \supseteq_{U_{K_1}} f$ such that $g \models_M K_1$,
	there is $h \supseteq_{U_{K_2}} g$ such that $h \models_M K_2$
$f\models_M \neg K_1$	iff there is no $\tilde{g} \supseteq_{U_{K_1}} f$ such that $g \models_M K_1$
$f\models_M K_1 \vee K_2$	iff there is a $g_1 \supseteq_{U_{K_1}} f$ such that $g_1 \models_M K_1$
	or there is a $g_2 \supseteq_{U_{K_2}} f$ such that $g_2 \models_M K_2$

8 Presuppositions (van der Sandt)

A proto-DRS is a triple $\langle U_K, C_K, A_K \rangle$, where

- U_K is a set of discourse referents
- $-C_K$ is a set of conditions
- $-A_K$ is a set of "anaphoric" (alpha-) DRSs.

9 Resolution of α -DRSs

Let K and K' be proto-DRSs such that K' is a sub-DRS of K. Let $\gamma = \alpha x K_s$ be an alpha-free alpha-DRS in K', and let K_t be a sub-DRS of K that is accessible for γ .

- (a) Accommodation: Remove γ from K', and extend K_t with U_{K_s} and C_{K_s} .
- (b) Binding: Let further $y \in U_{K_t}$ be a discourse referent that is suitable for γ . Then remove γ from K', and extend K_t with U_{K_s} and C_{K_s} and the condition x = y.

10 DPL: Interpretation

Terms:

 $\llbracket x \rrbracket^{M,h} = h(x) \quad \text{if } x \text{ is a variable} \\ \llbracket a \rrbracket^{M,h} = V_M(a) \quad \text{if } a \text{ is a constant.}$

Formulas:

$$\begin{split} & \llbracket R(t_1, \dots, t_n) \rrbracket^M &= \{ \langle g, h \rangle \mid h = g \text{ and } \langle \llbracket t_1 \rrbracket^{M,h}, \dots, \llbracket t_n \rrbracket^{M,h} \rangle \in V_M(R) \} \\ & \llbracket t_1 = t_2 \rrbracket^M &= \{ \langle g, h \rangle \mid h = g \text{ and } \llbracket t_1 \rrbracket^{M,h} = \llbracket t_2 \rrbracket^{M,h} \} \\ & \llbracket \neg \varphi \rrbracket^M &= \{ \langle g, h \rangle \mid h = g \text{ and ex. no } k \text{ s.t. } \langle g, k \rangle \in \llbracket \varphi \rrbracket^M \} \\ & \llbracket \varphi \land \psi \rrbracket^M &= \{ \langle g, h \rangle \mid ex. \ k \text{ s.t. } \langle g, k \rangle \in \llbracket \varphi \rrbracket^M \text{ and } \langle k, h \rangle \in \llbracket \psi \rrbracket^M \} \\ & \llbracket \varphi \lor \psi \rrbracket^M &= \{ \langle g, h \rangle \mid h = g \text{ and ex. } k \text{ s.t. } \langle g, k \rangle \in \llbracket \varphi \rrbracket^M \text{ or } \langle g, k \rangle \in \llbracket \psi \rrbracket^M \} \\ & \llbracket \varphi \to \psi \rrbracket^M &= \{ \langle g, h \rangle \mid h = g \text{ and for all } k \text{: if } \langle g, k \rangle \in \llbracket \varphi \rrbracket^M, \text{ then ex. } j \text{ s.t. } \langle k, j \rangle \in \llbracket \psi \rrbracket^M \} \\ & \llbracket \exists x.\varphi \rrbracket^M &= \{ \langle g, h \rangle \mid h = g \text{ and for each } k[x]g, \text{ there is an } m \text{ s.t. } \langle k, m \rangle \in \llbracket \varphi \rrbracket^M \} \\ & \llbracket \forall x.\varphi \rrbracket^M &= \{ \langle g, h \rangle \mid h = g \text{ and for each } k[x]g, \text{ there is an } m \text{ s.t. } \langle k, m \rangle \in \llbracket \varphi \rrbracket^M \} \end{split}$$

11 DPL: Truth, equivalence, entailment

- (a) Truth and validity:
 - A formula φ is true in M with respect to an input assignment g iff there is a h s.t. $\langle g, h \rangle \in [\![\varphi]\!]^M$.
 - A formula φ is *true in* M iff φ is true in M with respect to every input assignment.
 - $-~\varphi$ is valid iff it is true in every model structure.
- (b) Notions of equivalence:
 - Satisfaction set: $\langle \varphi \rangle_M = \{g \mid \text{exists } h \text{ s.t. } \langle g, h \rangle \in \llbracket \varphi \rrbracket^M \}$
 - s-equivalence (static equivalence): $\varphi \Leftrightarrow_S \psi$ iff for all $M, \ \langle \varphi \rangle_M = \langle \psi \rangle_M$
 - full equivalence (dynamic equivalence): $\varphi \Leftrightarrow \psi$ iff for all M, $\llbracket \varphi \rrbracket^M = \llbracket \psi \rrbracket^M$
- (c) Notions of entailment:
 - Static entailment: $\varphi \models_S \psi$ iff for all M, g: If φ is true wrt. M and g, then ψ is true wrt. M and g.
 - Meaning inclusion: $\varphi \leq \psi$ iff $\llbracket \varphi \rrbracket^M \subseteq \llbracket \psi \rrbracket^M$.
 - Dynamic entailment: $\varphi \models \psi$ iff for all M, g, h: if $\langle g, h \rangle \in \llbracket \varphi \rrbracket^M$, then there exists k s.t. $\langle h, k \rangle \in \llbracket \psi \rrbracket^M$.